RSC Advances

REVIEW

Cite this: RSC Adv., 2020, 10, 11652

Advances in passively driven microfluidics and labon-chip devices: a comprehensive literature review and patent analysis

Vigneswaran Narayanamurthy[,](http://orcid.org/0000-0001-6076-0106) D^{*abc} Z. E. Jeroish,^{de} K. S. Bhuvaneshwari, ^{df} Pouriya Bayat,^g R. Premkumar,^d Fahmi Samsuri^e and Mashitah M. Yusoff^h

The development of passively driven microfluidic labs on chips has been increasing over the years. In the passive approach, the microfluids are usually driven and operated without any external actuators, fields, or power sources. Passive microfluidic techniques adopt osmosis, capillary action, surface tension, pressure, gravity-driven flow, hydrostatic flow, and vacuums to achieve fluid flow. There is a great need to explore labs on chips that are rapid, compact, portable, and easy to use. The evolution of these techniques is essential to meet current needs. Researchers have highlighted the vast potential in the field that needs to be explored to develop rapid passive labs on chips to suit market/researcher demands. A comprehensive review, along with patent analysis, is presented here, listing the latest advances in passive microfluidic techniques, along with the related mechanisms and applications. **EXAMPLE MANUAL PROPERTIES AND ADVANCES IN PASSIVELY driven microfluidics and la

Stephen Richards and patent analysis**

Contents fisc Adv. 2020. 0 1.052 **and patent analysis**

Contents fisc Adv. 2020. 0 1.052 **and paten**

Received 10th January 2020 Accepted 20th February 2020

DOI: 10.1039/d0ra00263a

rsc.li/rsc-advances

Introduction

Handling small volumes of fluids is very important in highthroughput screening, diagnosis, and research applications.¹ Microfluidics is one way to handle small volumes of fluids between microlitres (10^{-6}) and picolitres (10^{-12}) .²⁻⁴ Hundreds of simultaneous biochemical reactions can be performed in a collection of microarrays arranged on a solid substrate which acts as laboratories, embedded in which are chips known as biochips.5,6 There are three main types of biochips: lab on chips (LOCs), DNA chips, and protein chips. LOCs employ a combination of one or more laboratory functions within a single integrated chip.⁷ Some fields utilizing LOCs, such as sub-micrometer and nano-sized channels, DNA labyrinths, single-cell detection and analysis,⁸ and nano-sensors, might become feasible,

"Department of Electronics and Computer Engineering Technology, Faculty of Electrical and Electronic Engineering Technology, Universiti Teknikal Malaysia Melaka, Hang Tuah Jaya, 76100 Durian Tunggal, Melaka, Malaysia. E-mail: vigjes@gmail.com; vigneswaran@utem.edu.my

g Department of Bioengineering, McGill University, Montreal, QC, Canada H3A 0E9

h Faculty of Industrial Sciences and Technology, University Malaysia Pahang, Kuantan 26300, Malaysia

allowing new ways to interact with biological species and large molecules. In addition, a large number of biochemical analyses can be screened at a faster rate in disease diagnosis and the detection of bioterrorism agents.⁹ Several reports have been published on the various aspects of these devices, including fluid transport, system properties, sensing techniques,¹⁰ and bioanalytical applications. Advantages $11,12$ include lower fabrication costs, allowing cost-effective disposable chips and mass production. Simple tests that could be performed by the bedside are known as point-of-care (POC) testing.¹³ The ultimate aim of this technique is to obtain results in a concise period at or near the location of the patient, so that the treatment plan can be adjusted.¹⁴ Microfluidics can be used for various lab experiments, such as drug testing and discovery,¹⁵⁻²³ filtration and separation of particles,²⁴ cell sorting and counting,²⁵⁻³¹ cell culture,³²⁻⁴⁰ pointof-care diagnosis, $41,42$ 3D printing, stoichiometry, and flow synthesis.^{43,44} Due to their simplicity with high throughput and very low reagent consumption,⁴⁵ microfluidic chips are vital components in research, for the delivery of accurate results.⁴⁶ Microfluidic chips are mostly made up of PDMS (polydimethylsiloxane). PDMS is commonly used because it is a transparent elastic polymer, permeable to oxygen and carbon dioxide.⁴⁷–⁵¹ Additionally, PDMS is now becoming a standard material as it can be easily fabricated for microfluidic devices (MFDs), and its high gas solubility, which obeys Henry's law, is a significant advantage of using PDMS material.⁵²

Microfluidic operation techniques

The techniques assisting fluid flow in an MFD are generally classified as active or passive.^{53,54} Active microfluidics^{55,56}

b InnoFuTech, No: 42/12, 7th Street, Vallalar Nagar, Chennai, Tamil Nadu 600072, India

c Centre of Excellence for Advanced Research in Fluid Flow, University Malaysia Pahang, Kuantan 26300, Malaysia

d Department of Biomedical Engineering, Rajalakshmi Engineering College, Chennai 602105, India

e Faculty of Electrical and Electronics Engineering, University Malaysia Pahang, Pekan 26600, Malaysia

f Faculty of Electronics and Computer Engineering, Universiti Teknikal Malaysia Melaka, Hang Tuah Jaya, 76100 Durian Tunggal, Melaka, Malaysia

involves the movement or transport of biological samples and analysis of those samples through an external power source/ field $57-59$ or actuators,⁶⁰ such as peristaltic pumps,⁶¹ electrokinetics,^{62,63} electro-wetting,⁶⁴ electro-osmotic pumps,⁶⁵ electrostatics,^{66,67} centrifugal and magnetic pumps⁶⁸ and some other large power sources to power the pumps and actuators.⁶⁹⁻⁷¹ Thus the complexity of structure and size is increased, which requires additional human resources. Hence, the probability of integrating active microfluidics with LOCs and (POC) applications has dropped off. To counter these drawbacks, $72-74$ the movement of the test sample is achieved either using fluid properties or passive mechanisms without any external supporting power sources. Hence, passive microfluidics⁷⁵ has been adopted and used to a large extent in modern-day research projects to avoid the use of external supporting power devices. This method is simple, easy to manufacture, and does not need any actuators or external power supplies, as it employs basic laboratory instruments, like micropipettes, and medical devices, such as syringe pumps. Review Were

involves in theorement or interaction control published on 23 March 2020. The control published on 23 March 2020 and the company of the control published on 23 March 2020 and the company of the company of the

Systematic literature search

A systematic literature search has been performed using Google Scholar with the following keywords: "passive pumping platform, passively driven microfluidics, pressure head driven microfluidics, and flow-driven microfluidics" throughout 2000– 2018. Fig. 1 presents a pie chart revealing the aggregate number of articles on passive microfluidics published from 2000 to 2018. This review article will be useful for researchers who plan further investigations in this field.

From Fig. 1, it is evident that pressure-driven, capillary, hydrostatic, surface-tension and vacuum-based methods are leading trends. From the search, articles were selected and some were hand picked based on their relevancy with an exclusive focus on the passively driven approach and they are presented according to their timeline. In 2002, David Beebe et al. published a short report on the fabrication of MFDs and the physics applied to passive valves, mixers, and pumps which facilitate fluid flow.⁵³ Due to the extensive usage of PDMS in MFDs, Sia et al. reviewed the advantages of using PDMS in miniaturized biological assay devices, such as efficiency and

spectral insights into cell biology, where the fluidic flow was obtained by applying a positive or negative pressure at the inlet or outlet, respectively.⁷⁶ Subsequently, Bayraktar et al. reviewed the available knowledge based on the areas that required additional investigation in pressure-driven and electro-osmotic flows in microchannels.⁷⁷ Later, Fiorini et al. in 2005 reported a review of different modes of on-chip operations, such as the pumping and valving of fluid flow; and the separation and detection of different chemical species that have been implemented in a microfluidic format.⁵⁴ Haeberle et al. reported platforms for LOC applications.⁷⁸ Eventually, a microfluidic cell culture was developed, which implied the use of surface tension, where a differential pressure was generated due to the different volumes in the inlet and outlet port to assist the fluid flow and which was based on concepts related to physical and microenvironments on passive pumping.⁷⁹ Additionally, Ahn et al. reported a short review in 2010 based on various methods of passive pumping and their applications to LOC biochemical analysis.⁸⁰

Furthermore, Gervais et al. focused on various techniques that have been adapted for passive pumping.⁷⁴ Later, Su et al. reviewed the latest advances in microfluidic platforms for POC testing in the context of infectious diseases, along with the integration of multiple functions into a single unit with full automation and analysed the challenges involved.⁸¹ Subsequently, Byun et al. summarized recent advances in pumping techniques for microfluidic cell culture in an effort to support current and potential users of microfluidic-based devices for advanced in vitro cellular studies.⁵⁷ The relevant biophysical laws, along with their experimental details and the designs of various passive separation techniques, were explained by Tripathi et al. in 2015.⁸² These separation techniques advanced the development of single-cell capture. Eventually, Narayanamurthy et al. focussed on the development of single-cell trapping using hydrodynamic effects for the purpose of developments in cell separation and rapid viral detection and explained its benefits.⁸³

In this article, we wish to discuss the current proposals, developments, updates, and future of passive microfluidic and LOC devices. The different methods adopted in every passively driven type of microfluidics are briefly covered, so that one can obtain a better and clearer knowledge of previous techniques.⁸⁴⁻⁸⁶ This also throws light on the advantages, flow rates and applications of all the techniques. The limitations of each method are also explained.

Patent analysis and current key market players in the field of microfluidics and lab-on-chip devices

A patent analysis was performed with the Google Patents search tool, using the keywords, passive AND (driven OR flow) AND (biochips OR microfluidics OR LOC), and the analysis is provided in Fig. 2. The key players in the microfluidics market are Semiconductor Energy Laboratory Co., Ltd. (US), Theranos, Inc. (US), Abbott Point Of Care Inc. (US), Micronics, Inc. (US), Danaher (US), Thermo Fisher (US), PerkinElmer (US), Roche (Switzerland), Biomicro Systems, Inc. (US), Incyte Fig. 1 Trends in passive microfluidics. Genomics, Inc. (US), Silicon Laboratories, Inc. (US), Tecan

Trading Ag (Switzerland), Aviva Biosciences Corporation (US), Eksigent Technologies, Llc (US), Nanostream, Inc. (US), International Business Machines Corporation (US), 10X Genomics (US), Accelerate Diagnostics, Inc. (US), Advanced Cell Diagnostics, Inc. (US), Affymetrix, Inc. (US), Agilent Technologies, Inc. (US), Amphasys AG (Switzerland), Angle Plc (UK), Beckman Coulter, Inc. (US), Becton, Dickinson, and Company (US), Bio-Rad Laboratories, Inc. (US), Clontech Laboratories, Inc. (US), Celsee Diagnostics (US), Enumeral (US), Epic Sciences (US), Fluidigm (US), Illumina, Inc. (US), Kellbenx Inc. (US), Merck KGaA (Germany), NanoString technologies (US), Qiagen NV (Netherlands), Sigma Aldrich (US), Thermo Fisher Scientific, Inc. (US), Wafergen Bio-Systems, Inc. (US), Yikon Genomics (China), Zephyrus Biosciences, Inc. (US), Dolomite Microfluidics (UK), GYROS PROTEIN TECHNOLOGIES AB (Sweden), Sphere Fluidics (UK), OPKO Health (US), Waters (US), thinXXS Microtechnology (Germany), Abaxis (US), bioMérieux (France), Dolomite Microfluidics (UK), Microfluidic ChipShop (Germany), Elveflow (France), Cellix (Ireland), Micronit Microtechnologies (Netherlands), MicroLiquid (Spain), MiniFAB (Australia), uFluidix (Canada), Micralyne (US), and Fluigent (France).⁸⁷

Passive microfluidic techniques

Passive microfluidics is an emerging technique with a tremendous scope that is being adopted more commonly in LOC and POC diagnosis due to the following characteristics:

• Easy fabrication: Fabrication of passive microfluidics is simple and easy, as it avoids complicated fabrication resulting in complex structures.

• Less expertise: Passive microfluidics operation does not usually require training or experience, as it is straightforward and easy to operate.

• No external power source required: Passive microfluidics does not involve any external power source for its working.

• Low cost: Passive microfluidics is substantially low in price due to less complicated procedures and no auxiliaries being involved.

• Compact and portable: Passive microfluidics is very compact and portable in size; hence, it can be driven almost anywhere.

Different techniques employed in the field of microfluidics and LOC devices to achieve passive operations are surface tension, pressure-driven, osmosis, capillary action, gravityinduced flow, vacuum suction, and hydrostatic pressure, as shown in Fig. 3. Each technique has its pros and cons. In the sections below, each technique is described in detail, and the articles are listed in year order.

Surface tension

In general, surface tension is defined as a property of the surface of a liquid that allows it to resist an external force due to the cohesive nature of water molecules. This cohesive forces between the liquid molecules are responsible for the phenomenon known as surface tension.⁸⁸

In microfluidics, the generation of strong passive flows can be achieved by selecting a suitable surface and liquid combinations that can create the required solid–liquid surfacetension gradients.⁸⁹ Mathematical models are required to finalize the design of the channel, so Makhijani et al. developed a numerical model to simulate the liquid filling due to the presence of surface tension in the liquid–air interface and demonstrated the application of disposable biochips for clinical diagnosis. It was mainly used for analysis and optimization to achieve the desired flow.⁹⁰ Subsequently, Walker et al. proposed a simple, semi-autonomous method of pumping fluids where devices producing small droplets, such as a pipettes, were required.⁹¹ Meanwhile, evaporation occurred during the surface-tension-based flow, which could be used to increase the concentration of the sample in the channel.⁹² Due to the requirement of microfluid mixing, for the purpose of drug delivery and research, Chen et al. demonstrated a micromixing device without the use of any active devices; hence, the surface tension of the fluid provided transport, merging, mixing, and stopping in the microchannel by varying the channel geometry.⁹³ Ward et al. analysed droplet formation using flow-

Fig. 3 Different approaches employed in passively driven microfluidics and LOC devices

focusing geometry and microfluidic technology and compared the two methods of supplying fluids using a syringe-pump methodology that dictated the volume flow rates and a method which controlled the inlet fluid pressure.⁹⁴ Later, Tan et al. controlled the droplets by the formation of a bifurcated junction in an MFD, and thereby controlled the chemical concentration in the droplet by the use of droplet fission.⁹⁵

Furthermore, a passive pumping technique was employed in a direct methanol fuel cell (DMFC), through passive fuel delivery, designed based on a surface-tension driving mechanism and integrated with a laboratory-made prototype to achieve fixed consumption depending on fuel concentration and power-free fuel delivery. Due to different surface-tension properties, water was separated from methanol through a Teflon membrane, and forward flow occurred in the capillary. This was believed by Yang et al. to be more applicable to future smallscale DMFCs in portable electronics.⁹⁶ Thanks to their analysis of channel pressure and flow, Berthier et al. reported that greater pressure created a large drop in output at the channel exit when a small droplet was placed on the entrance of the microfluidic channel.⁹⁷ Eventually, in 2008 Ivar et al. published an article that implied the use of surface tension to induce a pressure difference in the fluid that causes pumping, routing, and compartmentalization without the use of any additional micro-components. Moreover, they demonstrated the applications of patterning multiple monolayer cell colonies and threedimensional cell compartments and co-cultures.⁹⁸ Backflow is a serious issue faced in surface-tension-driven pumps, so Ju et al. explained the optimum conditions required to avoid

backflow in surface-tension-driven passive pumping by determining the ratio of inlet and outlet pressure during the occurrence of backflow.⁹⁹ Du et al. reported that the concentration gradient in the channel induced forward flow, and it was further enhanced by evaporation-induced backward flow. Thus, the gradient concentration generated was controlled by convection and molecular diffusion. This approach was particularly used for chemical and biological processes in portable MFDs, where long-range gradients are required.¹⁰⁰ Jane et al. analysed the flow rate with the Hagen-Poiseuille equation, thermodynamics, and the Young-Laplace equation where the flow rates could be controlled by channel geometry, dimension of inlet and outlet wells and hydrophobicity. Later, Chen et al. provided a clear idea about the surface-tension-induced flow rates, theoretical relationships among sample volume, induced flow rate, and surface tension of the drops at the inlet and outlet ports, and resistance to flow.¹⁰¹

As soon as the droplet was placed at the inlet port, it began to collapse due to varying velocity in the channel and it transformed from a smaller drop to a larger drop. Theoretically, the maximum flow rate was obtained at a contact angle of 90 degrees, but practically it was maintained between 30 and 60 degrees due to refilling. Resto et al. provided a clear idea of both theoretical and practical aspects of the pumping and the contact angle to achieve the maximum flow rate.¹⁰² The surface tension caused a pressure difference in the channel to induce fluid flow from the inlet to the outlet. Equilibrium of pressure in the channel led to the immediate arrest of the inflow. This sudden stop allowed its use in a wide range of biological applications from reagent delivery to drug-cell studies.¹⁰³ Jane et al. explained that the surface tension in the fluid induced the flow through the microchannels due to the change in volumes of fluid. Passive microfluidics with electrochemical sensors inside the microchannel was considered for LOC flow injection. Various factors affecting the flow in the microfluidic channel were also discussed. This was the first report on a passive pump based on flow injection analysis (FIA).¹⁰⁴ In 2010, Amy et al. integrated particle counting with a passive pumping mechanism by placing a 0.5 microliter drop of saline and sample fluid on the focussing inlet and the sample inlet, respectively. The surface tension in the fluid experienced a flow due to the change in volume. These flows to the reservoir traversed a pore that caused a change in resistivity, and the pulse was counted. Thus, particle counting was achieved with the help of surface-tension pumping.¹⁰⁵

Puccinelli *et al.* explained that the pumping process of a small drop placed at the inlet was due to the surface tension in the inlet fluid. They validated the performance of a complete, reliable, and repeatable cell-based biological assay. The robustness of each technique was also discussed.¹⁰⁶ Chung et al. described the involvement of surface tension, as well as evaporation, leading to the generation of passive pumping in a forward and backward direction with a concentration gradient a few centimeters long in the channel. Recent developments in microfluidic gradient generators were also described in their work.¹⁰⁷ Besides research, Lin et al. demonstrated the uses and applications of microfluidics in the fields of food, environment, and physiological health monitoring.¹⁰⁸ Berthier et al. suggested that the surface tension of the fluid enabled a short-term laminar flow patterning in multiple fluids when the sample was loaded in any sequence. Numerical simulations and practical experiments were conducted to study the laminar behaviour. This method was well suited to a cell-based assay and reduced the complexities of laminar flow patterning (LPF).¹⁰⁹ In 2012, Resto et al. developed inertia-enhanced passive pumping that reduced fluid exchange and inertia-activated flow, which initiates the flow in an empty channel where fluid flow took RSC Advances

applications from rangent delvery to dingvelil and
les.^{net} pure public transfer more than the intermediations are respective to the
system published on 2020 and the system intermediations of the intermedia

place due to surface tension. They also analysed the transfer of momentum to the incoming fluid and the effect which induced the pumping mechanism.¹¹⁰

Microdevices are capable of targeted focal delivery of chemicals for axonal growth studies. Hence, Kuo et al. varied the drop volume to passively drive the flow into the microchannel. With this manipulation technique, the bio-chemicals delivered were combined with neuronal cells, and the required flow rate was achieved.¹¹¹ Groot et al. enabled the dynamic culture and analysis of tissues in a hanging drop example, which employed surface tension as the driving force with two droplets, namely the culture droplet and the userinterface droplet.¹¹² Computer simulations were used to give detailed information on flow patterns and physical phenomena under different conditions. The pumping process was divided into three planes with deceleration followed by acceleration and deceleration that relied on the physical properties of the operating fluid, and geometrical characteristics of the channel.¹¹³ Fig. 4 shows an MFD utilizing surface tension for passive operation. The latest reports on passive MFD using surface tension techniques are summarised in Table 1.

Limitations. As the fluid droplet at the inlet reduces, the surface tension decreases causing a decrease in fluid flow. So refilling is necessary for continuous flow.⁵⁷ Additionally, the presence of reflected light and mirage effects in millimetre-wide spherical caps reduce the accuracy of goniometer measurement.⁹⁷

Pressure-driven

Fluid pressure is a measurement of the force per unit area. Pressure in liquids is equally divided in all directions; therefore, if a force is applied to one point of the liquid, it will be transmitted to all other points within the liquid.¹¹⁴ MFD and LOC devices employing pressure for their passive operations are shown in Fig. 5. In a passive pressure-driven technique, the pressure created in the reservoirs to drive the sample is achieved either by pipetting or by a finger-force pressure.¹¹⁵ Liu et al. reported a twisted microchannel with chaotic advection that possessed high potential mixing even for fluids with a low

Fig. 4 (i) The types of surface-tension-driven passive microfluidics in different studies, which include the recession of a drop in two phases along with a front view and side view of the microfluidic system in passive pumping (this figure has been adapted from ref. 113 with permission from ELSEVIER, copyright: 2018). (ii) A schematic diagram of surface tension driven microfluidics. The flow direction is basically determined by the radius balance of the droplets; the bold arrows in the figures denote the flow direction (this figure has been reproduced from ref. 99 with permission from IOP, copyright: 2008). (iii) Different surface-tension-driven flows: (a) pulsatile forward flow, (b) constant forward flow, (c) constant forward-flow with additional liquid packets, (d) alternating (forward/backward) flow, (e) whole-channel fluidic exchange achieved with alternating constant flow by two nozzles, and (f) instantaneous flow reversal using alternating (forward/backward) flow (this figure has been adapted from ref. 110 with permission from the Royal Society of Chemistry, copyright: 2012).

Table 1 Recent surface-tension-driven passive pumping techniques in microfluidics

Table 1 (Contd.)

Reynolds number.¹¹⁶ Ahn et al. suggested the fluid control technique and verified that the low-pressure drop in the fluid tended to maintain the flow without any complicated pumps.¹¹⁷ Also, Jeon et al. described the design and fabrication of passive valves and pumps, which used the pressure-driven mechanism instead of electro-osmotic pumps. The fabrication included aligning, stacking, and bonding of a patterned membrane.¹¹⁸ Rush et al. established a 2D serpentine channel with the flow of low-Reynolds-number Brownian solute particles.¹¹⁹ Later, Moorthy et al. developed an on-chip porous filter that separates minimal volumes of biological fluids in real-time applications and analysis.¹²⁰ Also, Hu et al. investigated the relationship RSC Advances Review

> drop decreased.¹²¹ Chen et al. explained that a wavy-wall section incorporated within the microchannel developed a centimetre-long high concentration gradient by increasing the interfacial leads.¹²² Jiang et al. explained the push or pull in the sample fluid due to a negative or positive pressure that a syringe pump would create.¹²³ Hattori et al. confirmed that fluid flow commenced only when the pressure was applied to the fluid by using a syringe pump or micropipette through an air vent filter.¹²⁴ In addition, when a finger-powered pressure of about 3-4 kPa was applied at the inlet, sample movement occurred.¹¹⁴ In their investigations, Davey et al. recommended a system where the inlet and the outlet were a hydrophobic and a hydrophilic needle, respectively, and the channel was made of a hydrophilic region where the fluid from the inlet traversed the channel and reached the outlet.¹²⁵ Tice et al. reported an electrostatic microvalve with passive components embedded in them, which was used to regulate the pressure in hydraulic control lines and actuate pressure-driven components.¹²⁶

> between the pressure drop in the rough channel and smooth channels and also the pressure drop due to a change in height. It was found that in a rough channel the pressure drop increased and when the channel height increased the pressure

> Finger-power integrated pumping systems had been utilized to eradicate the limitations produced by the use of external pumps. Pressure generated inside the pressure chamber played a vital role in determining the efficiency of finger-powered pumps.¹²⁷ Thus the requirement for pre-evacuation of PDMS devices in a vacuum chamber was eliminated. Thereby, the design of a simple POC pumping method using a single-layer structure where the dead-end microfluidic channel was partly surrounded by an embedded microchamber, with a thin PDMS wall separating the dead-end channel and the embedded microchamber, was reported by Xu et al.¹²⁸ But the working liquid created a reduced pressure in the analytical channel and induced sequential sample flow into the microfluidic circuits. Kokalj et al. reported simplified activation by fingertip pressure with no external power or control for a wide range of applications in POC diagnostic settings.¹²⁹ Jeong et al. developed an onchip microflow control technology with the ability to mimic in vivo conditions at an in vitro microscale for long-term tissue culture with a continuous flow rate. The passive flow was initiated using a siphon effect, and a yarn flow resistor to regulate the flow rate in the microchannel.¹³⁰ Thanks to implantable drug delivery systems, a micropump for controlled, automated

Per View March 2020. Published on 23 March 2020. Downloaded on 23 March 2020. Downloaded on 12/2024 9:08:56 PM. This article is licensed under a Creative Commons Attribution 3.0 Unported License. **View Article is licensed**

Fig. 5 (i) (a) An integrated human-powered pumping system. By pushing the deformable chamber, mechanical pressure infuses the solution from the inlets to the outlets; (i) (b) the pumping procedure of the finger-powered pump with push-and-release actions. (ii) Fabrication via a multilayer soft lithography process; (ii) (a-f) the device consists of three layers of PDMS; (ii) (q) a fabricated PDMS pumping system; (ii) (h) a fabricated prototype via the injection moulding process (figures (i) and (ii) have been adapted from ref. 127 with permission from the Royal Society of Chemistry, copyright: 2014). (iii) Suction-cup-driven equipment-free fluid pumping: (a–d) finger-triggered pumping and reversible integration of the PDMS suction cup to the MFD (figure (iii) has been reproduced from ref. 132 with permission from SPRINGER, copyright: 2018). (iv) A self-powered imbibing microfluidic pump by liquid encapsulation (SIMPLE): (a) sequential pump operation and (b) an experimental presentation. (c) Initially, the chip is prefilled with the working liquid (blue) through the inlet denoted by 25 thick blue arrows and encapsulated by impermeable protective foil patches (green circles). Before activation, the foil is removed, the sample (red) is deposited over the inlet hole, and temporary finger force can activate the pump. When the working liquid touches the paper, the finger can be removed, and the pump is activated. The pump works until the working liquid saturates the paper or until all of the fluid has been sucked into the paper (figure (iv) has been adapted from ref. 129 with permission from the Royal Society of Chemistry, copyright: 2014).

inner-ear drug delivery with the ultimate aim of producing a long-term implantable/wearable delivery system was investigated by Tandon et $al.^{131}$ Currently accessible pressure-driven approaches in passively driven microfluidics are summarised in Table 2.

Satoh et al. in 2016 reported multiple medium-circulation units on a single MFD that were driven only by two pneumatic pressure lines with three independent culture units, in which the cells were cultured under medium circulation flow. The authors stated that pneumatic pressure could be easily distributed to multiple wells in a reservoir with a common gas-phase space without any changes in tube connections.¹³⁴

Zhang et al. developed a microfluidic passive flow regulator with an in-built five-layer structure valve for high-throughput flowrate control in microfluidic environments by constructing a gas-driven flow system and analyzed the flow regulation.¹³⁵ Moon et al. investigated a passive microfluidic flow-focusing method to generate water-in-water aqueous two-phase system (ATPS) droplets without the involvement of any external components. This was the first microfluidic technique that formed low interfacial tension ATPS droplets without applying external perturbations.¹³⁶ Ryu et al. examined a closed-loop operation of inertial microfluidics, which could dissociate clinical airway secretions and isolate/enrich immune-related

Table 2 Recent pressure-driven approaches in passively driven microfluidics

cells for in vitro downstream assays. They found their applications in clinical in vitro cell-based biological assays of various pulmonary diseases like acute respiratory distress syndrome, pneumonia, cystic fibrosis and bronchiectasis.¹³⁷

Lee et al. also developed a negative pressure-driven fluid flow generated by a simple finger-triggered operation where the PDMS suction cup was placed at the outlet of the device and dispensed the fluid at the inlet.¹³² A new infusion-based simple method (ISIMPLE) for drug delivery into the skin was developed by Dosso et al. with a self-contained skin patch without any external driving source, where the expelled air increased the pressure due to the extreme flexibility of the design and manufacture. The ISIMPLE concept offered enormous opportunities for entirely autonomous, portable, and cost-effective LOC devices.¹³⁹ Later, Liu et al. developed a PDMS pump that utilized the air released from the aerated PDMS to create a positive pressure in the MFD.¹⁴⁰

Limitations. The application of external pressure using a finger might affect the accuracy and repeatability of the assays due to pressure difference, and multi-step diagnostic assays may not succeed via hand-powered mechanisms since several reagents/buffers need to be driven in a controlled manner.¹⁴¹

Osmosis

Osmosis is the spontaneous net movement of solvent molecules to a region of higher solute concentration in the direction that tends to equalize the solute concentrations on both sides through a selectively permeable membrane. Permeability depends on solubility, charge, or chemistry, and solute size. Water molecules diffuse through the solute from the solvent layer.¹⁴² Bruhn et al. demonstrated the development of devices that are capable of pressure generation based on the osmosis principle, which could be made from available low-cost materials.¹⁴³ Some MFD and LOC devices using osmosis as a passive approach for their operation are shown in Fig. 6.

Later, Good et al. integrated and analyzed a polymeric microfluidic device in a portable mechanical micro-pumping system that used fluid-responsive polymer particles as an actuator, without external power.¹⁴⁴ In 2009, Xu et al. reported that, when a semi-permeable membrane was sandwiched between the inner osmotic reagent chamber and the outer water chamber, the water flow to the osmotic reagent chamber via the semi-permeable membrane facilitated the flow of fluid in the channel by the process of osmosis.¹⁴⁵ Furthermore, stable concentration gradients are required for cell analysis and culture. The development of a microfluidic platform provided stable concentration gradients for cells of various signaling molecules for more than a week with only the least amount of handling and no external power source. Later, Park et al. optimized the osmotic pumping performance by balancing the capillary action and hydraulic pressure in the inlet reagent reservoirs.¹⁴⁶ Updates on osmotic-driven passive pumping techniques in microfluidics are summarised in Table 3.

Fig. 6 (i) Osmotic pump schematic diagram (this figure has been adapted from ref. 147 with permission from the Royal Society of Chemistry, copyright: 2009). (ii) Osmotic pump operation (this figure has been reproduced from ref. 57 with permission from Wiley, copyright: 2014). (iii) An operational diagram of the system, including the pump unit and the Poiseuille flow with constant wall shear stress (this figure has been adapted from ref. 148 with permission from IOS Press, copyright: 2010). (iv) Experimental setup with four components, namely concentration gradient, pipette tips, osmotic pumps and coiled tube (this figure has been reproduced from ref. 146 with permission from Alpha Med Press, copyright: 2009). (v) A microfluidic fuel cell (MFFC) system using an osmotic pump (this figure has been adapted from ref. 149 with permission from IOP, copyright: 2018)

Limitations. An osmotically driven mechanism needs a complex setup compared to surface-tension, capillary, and gravity-driven setups.⁵⁷ In osmotic drug delivery systems refilling the reservoirs was mostly impossible or complicated with the constant drug delivery rate.¹⁴⁴ The development of an additional reservoir for the solvents increased the device complexity for operation in any environment.¹⁵⁰

Capillary

Capillary action is defined as the movement of a fluid within the spaces of a porous material due to the intermolecular forces between the liquid and the surrounding solid surfaces that enables the liquid to flow in narrow spaces without the assistance of, or even in opposition to, external forces like gravity.⁸⁷

Juncker et al. reported a capillary pump assisted capillary flow microfluidic system, where the flow was activated from the open and closed channels of the device.¹⁵¹ MFD and LOC devices incorporating the capillary technique are shown in

Fig. 7. Simultaneously, a microfluidic capillary system was presented for the continuous transport of fluid using capillary force, when the fluid was placed in the service port.¹⁵¹ Mixing of fluids is necessary for drug delivery and research. So, Hosokawa et al. reported an MFD which used capillary force for pumping.¹⁵² To avoid clogging by fluids, Kim et al. presented a capillary passive retarding microvalve at the junction of the microfluidic channel where the propagation occurred only after the merging of two fluids.¹⁵³ An exact discussion of interface motion driven by capillary action in a microchannel was reported by Ichikawa et al. where a dimensionless variable of the driving force was used to predict the interface motion.¹⁵⁴ In order to maintain and control the flow properties of capillary systems (CSs), Zimmermann et al. developed a design for capillary pumps. These capillary pumps were designed to have a small flow resistance and were preceded by a constricted microchannel, which caused flow resistance.¹⁵⁵ Subsequently, Suk et al. developed a technique to control the autonomous

term cell culture

capillary flow with a passive method where the flow could be retarded with appropriate hydrophobic patterns in hydrophilic channel surfaces. The microfluidic system was designed in such a way that it contained two planar parallel surfaces, separated by spacers.¹⁵⁶

Flow rates may vary in different substrates, so Zhu et al. reported a study of capillary flow rate in several substances, including glass, polycarbonate (PC) and polydimethylsiloxane (PDMS) to measure the contact angles and to examine the longevity of capillary flow in PDMS and PC chips to give better clarity in measuring the flow rates.¹⁵⁷ Lynn et al. realized a pressure difference arising from the small curved meniscus at the bottom of the outlet reservoir that drove the fluid with a constant fluid flow for more than an hour.¹⁵⁸ Later, Gervais et al. described the fluid flow from high capillary pressure to low capillary pressure and increased the channel width at each level to reduce the friction, thereby leading to a high flow rate.¹⁵⁹ Mukhopadhyay et al. proposed a microchannel bend in polymethylmethacrylate (PMMA) of different widths. The effects of channel aspect ratio and different separation angles were studied for fluid flow.¹⁶⁰ Eventually, Alphonsus et al. explained in a short review on microfluidic immunoassay that the capillary pressure in the channel pushed the sample, causing the fluid to flow within the device.¹⁶¹ Kim et al. realized that the surfactant-added PDMS could be used to increase the hydrophobicity of PDMS to increase the filling rate of blood by capillary action.¹⁶² Souza et al. fabricated a toner-based microfluidic device in which the fluid flowed towards the outlet as soon as the serum was placed in the sample inlet.¹⁶³ Later, Horiuchi et al. also developed an immunoassay chip which consisted of vertically integrated capillary tubes to create negative pressure and pump the fluid towards it.¹⁶⁴ Once the fluid had been placed in the inlet well, Kim et al. verified the flow timing control and direction of multiple solutions in the channel.¹⁶⁵ Review Preview Review Preview Preview

Kistrup et al. reported aspects of using rapid prototyping instead of pilot (mass) production. They included the fabrication of the microfluidic system that employed injection moulding and ultrasonic welding in which the fluid flow was assisted by the capillary pressure at the interface nozzle.¹⁶⁶ Berthier et al. proposed the onset of the suspended capillary flows (SCF) and the viscous friction at the walls using the force balance between the capillary forces that drove the flow.¹⁶⁷ Plasma separation is possible in passive pumping microfluidic technology. Madadi et al. demonstrated a self-driven blood plasma separation microfluidic chip, which was capable of extracting more than 0.1 μ l of plasma from a single droplet of undiluted fresh human blood $(5 \mu l)$ with high purity without any external pumps.¹⁶⁸ Nie et al. reported a flexible microfluidic device that filled the channel through capillary force to provide continuous fluid pumping through an evaporation micropump. The hexagonal arrangement at the pore array drove the fluid flow and automatically absorbed liquid through a filter paper interface.¹⁶⁹ Mukhopadhyay et al. described a leakage-free PMMA fabricated MFD with microchannel bends with the effect of surface wettability on surface-driven capillary flow. This type of microfluidic system was utilized in blood cell

Fig. 7 (i) Schematic diagrams of a microfluidic device for self-propelled continuous-flow PCR: (a) concept diagram; (b) a cross-sectional view of the microfluidic device. (c) A photograph of the fabricated microfluidic device (this figure has been reproduced from ref. 182 with permission from Elsevier, copyright: 2015). (ii) A yarn flow resistance (YFR)-regulated microflow control system: (a) a schematic diagram showing the siphon effects in the yarn-capillary-resistance-driven micropump system; (b) a schematic diagram of the water-head-difference-driven siphon effect controlled by the YFR; (c) a photographic image of a yarn capillary regulator; (d) the microfluidic device prepared with a YFR (this figure has been adapted from ref. 130 with permission from the Royal Society of Chemistry, copyright: 2014).

separation from whole blood.¹⁷⁰ Maxime Huet et al. developed and integrated a biological protocol to observe RBC's agglutination in POC analysis. This work proved that the agglutination of blood began directly within the chip containing embedded reagents where a correlation-based indicator was used to conserve both spatial information and image quality.¹⁷¹ Later, Bunge et al. reviewed the utilization of symmetrical surface phase guides (SSPG), where the wall-less channels were generated by patterning hydrophobic phase guides on both sides of the chip to induce liquid propagation with the help of the capillary effect.¹⁷² Wu et al. generated flow-focusing droplets through the capillary effect to reduce the requirements of subsequent systems in addition to high flexibility.¹⁷³

Zhai et al. developed a microfluidic device, which was insensitive to backflow due to the integration of a syringe pump to balance the capillary pressure within the channel.¹⁷⁴ A study

on the microfluidic self-flowing chip to understand the influence of micro-scale topographies was reported by Xie et al. According to this work, the flow rate increased with increasing gradient on the surface and the flow speed was 40 times greater with high efficiency.¹⁷⁵ Vasilakis et al. reviewed a simple highspeed filling passive capillary pump integrated with lab-onprinted circuit board technology (Lo-PCB), with induced capillary pressure to produce stable flow rates.¹⁷⁶ Akyazi et al. developed a new concept for fluid flow manipulation in micro paper-based analytical devices (PADs), where the ionogel (considered to be a negative passive pump) could drive fluids by the swelling effect, which controlled the flow direction and volume to the outlet.¹⁷⁷ Frimat et al. described a new single-cell trapping procedure within the micro sieve electrode array (SEA) through capillary phenomena for an organized positioning of neurons to produce higher biocompatibility.¹⁷⁸

Table 4 Updates on capillary-based passive pumping in microfluidics Table 4 Updates on capillary-based passive pumping in microfluidics

extracted plasma

applications

Fig. 8 (i) (A) A compact, simple, and disposable device for passively driven sperm sorting; (B) fluid flow used to sort sperm based on their ability to cross the passively driven laminar fluid stream created by a hydrostatic pressure difference between the inlet and outlet (this figure has been adapted from ref. 186 with permission from ACS Publications, copyright: 2003). (C) A compact, passively driven microfluidic device with a sideview and top-view schematic diagram of the generation of hydrostatic pressure differences (this figure has been adapted from ref. 198 with permission from Springer, copyright: 2007). (D) The junction showing sperm movement from an input (reservoir 2) to an outlet (reservoir 3) (this figure has been reproduced from ref. 199 with permission from ELSEVIER, copyright: 2015). (ii) (a, b) Illustrations of pipette Petri dish single-cell trapping (PP-SCT) or tilt microfluidic trapping; (c, d) the side and top view, respectively, where θ is the tilt angle, h is the height of the inlet, D is the distance between the biochip outlet side edge to the Petri dish wall along the diameter, and Sl is the glass slide length (this figure has been adapted from ref. 196 with permission from MDPI, copyright: 2018).

Mei et al. developed a capillary-based open microfluidic device (COMD) for monodispersed droplet generation, from gas bubbles to highly viscous polymer solutions to provide high throughput in industrial emulsification. Capillary action was used as a portable sidewall of another microchannel with controllable size.¹⁷⁹ Kim et al. described a liquid additive, which passively controlled the velocity of cells within a detectable range during capillary sample loading, thereby eliminating the need for bulky and expensive pumping equipment. It also required the adoption of an immune bead assay, which was quantified with a portable fluorescence cell counter based on a blue-light-emitting diode.¹⁸⁰ Moonen et al. investigated capillary-based passive pumping for optimized neuronal cell trapping across a microsieve with gentle velocity profiles and

Table 5 Recent developments in gravity-based passive pumping in microfluidics

high survival rates.¹⁸¹ Reports on capillary-based passive pumping in microfluidics are summarised in Table 4.

Limitations. Though the capillary circuit and capillary elements contribute many characteristics to microfluidics, they are unable to deliver self-regulated flows for performing advanced functions.¹⁸⁴ The capillary action depends on the surface tension and adhesion of the analyte to the channel surfaces.¹⁵¹ The concentration of fluid in the outlet reservoir limits the overall flow duration; however, to alleviate this, multiple outlet reservoirs are used to reduce the rate of concentration in each reservoir to maintain longer flow duration.¹⁵⁸

Gravity-driven flow

This is a technique in which the fluid flow is driven or assisted by the earth's gravity, depending on the viscosity of the fluid and the height of the inlet from the surface. A comfortable and straightforward analysis of the flow rate in the MFD can be determined with the help of the gravity-driven flow principles which accelerate the passive pumping system was reported by Mäki et al. in 2014.¹⁸⁵ The microfluidics and LOC devices utilizing the gravity for their passive operations are shown in Fig. 8.

In 2003, Cho et al. described a simple disposable polymeric microscale integrated sperm sorter (MISS) to isolate sperm from semen, which was unattainable by traditional sperm-sorting methods.¹⁸⁶ Similarly, Suh et al. explained the purpose of obtaining the motile sperm through gravity-driven flow with increased morphology from normal semen.¹⁸⁷ Not only sperm but blood cells could be counted using a gravity-driven MFD that was fabricated using UV laser ablation and resin film lamination by Yamada et al. In 2005.¹⁸⁸ Huh et al. developed a unique combination of a simple, self-contained microfabricated device using field-driven separation with microhydrodynamics-assisted separation, where the earth's gravity was used to drive the fluids across the channel to assist in separation.¹⁸⁹ For cell culture, Lee et al. designed a compatible passive gravity-driven MFD with long-term continuous cell culture perfusion, which was adapted from the standard 96-well plate format to remove tubing and connectors.¹⁹⁰

In 2010, Zhang et al. presented a gravity-actuated technique where an oil phase was loaded into the infusion set and then the water phase was pumped into the PTFE (polytetrafluoroethylene) tubing by the gravity of the oil phase.¹⁹¹ Thereby, Sung et al. developed a gravity-induced-flow MFD to provide longterm flow by eliminating the bubble formation based on the mathematical PK-PD (pharmacokinetic/pharmacodynamic) model.¹⁹² Abaci et al. in 2014 developed a pumpless recirculating gravity-driven human skin equivalent (HSE)-on-a-chip platform that was simple to fabricate, handle and operate when placed on a rocking platform.²² A way of inducing fluid flow, by elevating the inlet of the channel against gravity by placing it on a rocking platform was demonstrated by Esch et al. in 2015.¹⁹³ A compactly configured differential flow resistance microfluidic single-cell trapping device with a shorter flow path was introduced and demonstrated by Jin et al. to increase the speed and

throughput (in both mathematical and numerical simulations).¹⁹⁴ James et al. developed an MFD with efficient trapping of single cells through hydrodynamic flow by positioning the microwells along the flow path, which acted as a mechanical barrier. The hydrodynamic flow inside the channel was analyzed with Comsol Multiphysics with different boundary conditions for varying particle sizes.¹⁹⁵ Simultaneously, Narayanamurthy et al. described the rate of single-cell trapping based on the shape of the channel in a passive biochip and concluded that hexagonally positioned microwells possessed high single-cell capture (SCC) percentages. The SCC potential of microfluidic biochips was found to be an improvement over straight channels, branched channels, or serpentine channels. Multiple cell capture (MCC) began to decrease from the straight channel, branched channel, or serpentine channels.¹⁹⁶ Kim et al. presented a design for gravity-driven microfluidic systems that could generate self-switching pulsatile flows to mimic physiological blood flow pulsing.¹⁹⁷ Comprehensive developments in gravity-based passive pumping in microfluidics are summarised in Table 5. Review Wavie article. The control of the

Limitations. For specific cell culture applications, dynamic or pulsatile flow was necessary, while gravity-driven microfluidic systems could only generate continuous flow.⁵⁷ However, with the insertion of a periodic rocking device, an active pump would be suitable to produce a dynamic flow.¹⁹² Upon tilting, this method for establishing an air–epidermal interface within a gravity-driven flow system is highly complex. Hence, the reservoir volume was subjected to minor adjustments and properly levelled surface for tilting.²²

Fig. 9 A pumpless MFD. (A) A schematic 3-D image of the PL MFD, showing the sample tank, tissue inlet, resistance circuit, and sample outlet, and an enlarged view of the portion encompassing the tissue chamber. (B) Pictures of the device. On the right, a closer view of the tissue chamber and resistance circuit. (C) A low-lateral view of the device demonstrating the medium-flow route, finally dropping down to the collecting dish (this figure has been reproduced from ref. 205 with permission from Springer, copyright: 2017).

Hydrostatic pressure

Hydrostatic pressure is the force exerted by a fluid at equilibrium at a given point acting with equal magnitude in all directions, due to the force of gravity. Hydrostatic pressure increases in proportion to the depth measured from the surface because of the increasing weight of the fluid, exerting a downward force from above.²⁰¹

Weigl et al. presented hydrostatic pressure-driven microfluidic elements, including mixers, valves, and detectors that were employed in ultra-low-cost disposable qualitative and semi-quantitative medical and environmental assays for the home, office, and field use, and for sample or reagent preparation tools to provide processed liquids for downstream analysis.²⁰² Subsequently, a microfluidic cartridge was planned for the extraction of small molecules by the hydrostatic pressure from the mixture of small and large molecules.²⁰³ For the culture medium, Marimuthu et al. developed a pumpless perfusion microfluidic chip that could deliver a constant flow rate with reduced pressure due to the intravenous (IV) setup used at the inlet, over the siphon-based gravity-driven micro fluidics.²⁰⁴ Later, Seo et al. employed hydrostatic pressure to sort motile sperms of three species, namely bull, mouse, and human, with an average sorting rate.¹⁹⁸ The culturing of mouse testis tissue and spermatogenesis in a hydrostatic pressure environment were developed by Komeya et al. In addition, researchers used a resistance circuit to induce slow and longlasting medium flow in the channel.²⁰⁵ MFD and LOC devices employing hydrostatic pressure for their passive operations are shown in Fig. 9. Comprehensive reports on the hydrostatic pressure-driven passive pumping technique in microfluidics are summarised in Table 6.

Limitations. In a few cell cultures and trapping experiments, a more accurate flow rate was not obtained due to the reservoir

Fig. 10 A hybrid PDMS utilizing permeability and capillary effects for fluid flow (this figure has been reproduced from ref. 225 with permission from IOP, copyright: 2009).

Fig. 11 (i) Blood separation utilizing gas solubility and the permeability of PDMS. [A] Self-priming, self-contained, tether-free SIMBAS. [B] Schematic diagrams of the proposed device. (B-a) An overview of the experimental setup using the proposed device. The top layer is a PDMS cover with an inlet and a tape-sealed outlet, and is bonded irreversibly with a bottom fluidic layer. (B-b) A top view and cross-section view. The separation chamber is divided into ten segments of equal volumes by nine phase guides at the bottom. Cylindrical posts are used to prevent the collapse of the pneumatic chamber when it is evacuated by the manual syringes. w and S stand for the PDMS wall thickness and the overlap area between the pneumatic chamber A and the separation chamber, respectively. The overlap area (S), where the flux of air diffuses, is calculated from the overlap length (l) multiplied by the chamber height (h). Drawings are not to scale. (B-c) Experimental steps. (ii) Different types of vacuum-driven power-free micro-pumping methods utilizing the gas solubility or permeability of PDMS. (A-1) A 2D micro-pumping design utilizing the gas solubility of PDMS. A whole PDMS device is pre-evacuated in a vacuum environment. (A-2) A 3D micro-pumping design utilizing the gas solubility of PDMS. A PDMS slab is pre-evacuated in a vacuum environment. See also Fig. 1A. (B-1) A 3D micro-pumping design utilizing the gas permeability of PDMS. External vacuum pumps are connected to the ports in the control channels. (B-2) A 2D micro-pumping design utilizing the gas permeability of PDMS. A hand-held syringe can generate a vacuum environment (figures (i) and (ii) have been adapted from ref. 214 with permission from the Royal Society of Chemistry, copyright: 2015).

design of the device. This could be modified with suitable adjustments in the diameter of the reservoir with the constant supply of fluids to the inlet.²⁰⁵

Vacuum driven

A vacuum refers to any space in which the pressure is lower than atmospheric pressure (negative pressure). Vacuum-driven devices use the ability of an MFD to suck the sample through negative pressure without any extra on/off-chip microfluidic units. Low vapour pressure and degassing become essential

when the vacuum pressure falls below this vapour pressure. Degassing is the process of removal of any gas in the channel through permeability or solubility within the membrane to generate a vacuum.²⁰⁶ Song et al. worked to produce a better demonstration of vacuum degassed flow in POC applications using a PDMS-based material, coated with Parylene C.²⁰⁷

Later, Monahan et al. developed a channel outgassing technique, where the channel was evacuated, and the negative pressure generated inside the channel assisted the flow with 90% efficiency in eliminating bubble formation.²⁰⁸ A new powerfree pumping method for PDMS MFD was developed by

Table 7 Recent works on vacuum/permeation driven passive pumping in microfluidics

Hosokawa et al. to overcome a significant issue in the detection of gold nanoparticle DNA analysis.⁷⁵ Subsequently, they presented an on-chip heterogeneous immunoassay with a simple structure and operational procedure. Redissolution through the microchannel walls developed the capacity to drive the solution movement and prevent air bubble trapping.²⁰⁹ Dimov et al. reported a microfluidic blood analysis system where the plasma was separated by trapping the RBC and WBC in a trench, and the inlet fluid was pumped due to the suction of the chamber, as a result of pre-evacuating the channel.²¹⁰ Liang *et al.* developed a degassed channel with negative pressure to pump the fluid irrespective of the surface tension of the fluid. Before sample loading, channel geometry, surface area, PDMS thickness, exposure area, vacuum degassing time, and post-vacuum idle time when the device was exposed to atmospheric conditions were inspected.²¹¹ Eventually, Li et al. designed a PDMS modular pump in a vacuum desiccator with high flexibility and reduced fabrication complexity to create negative pressure in the channel for sample movement.²¹²

Furthermore, Li et al. developed a self-powered one-touch nger-press-activated blood extraction system based on the negative pressure-driven force developed in the pre-vacuum actuator.²¹³ Xu et al. designed a vacuum-driven power-free MFD that depended on the gas solubility or permeability of PDMS that restored the air inside it and encouraged the transfer of air into a vacuum.²¹⁴ Also, Li et al. worked on the development of a self-powered PDMS-based microfluidic droplet generator with mono-dispersed droplet generation and multi-sample introduction in a controlled way.²¹⁵ A simplified and inexpensive passive microfluidic channel with excellent analytical performance to carry out microflow injection analysis (mFIA) was investigated by Agustini et $al.^{216}$ Subsequently, Liu et al. developed a paraffin wax and glass MFD through higher driving pressure to maintain longer working times where the inlet was exposed to air with a slower decline in flow rate.²¹⁷ Li et al. proposed a high-pressure MFD to drive the fluid using gas permeation and suppressing the generation of bubbles under high temperatures.²¹⁸ Then, a power-free and self-contained fluid reactor array that performed parallel fluid loading, metering and mixing through pre-degassed PDMS and the change in capillary force due to sudden narrowing of the channel cross-section was developed by Liu et al.²¹⁹

Diffusion. This is the movement of solute particles from a region of higher concentration to a region of lower concentration due to the random motion of atoms or molecules with or without a semi-permeable membrane. Warrick et al. compared the theoretical and experimental data of microchannels and standard wells on the metrics of sample washing and experimental error in treatment concentrations.²²⁰

Permeation. Verneuil et al. described the process of water permeation in microstructures through silicone which has a strong influence on fluid displacement.²²¹ Randall et al. confirmed the use of lubrication approximation to solve gapaveraged velocity while transferring water from a single rectangular channel into a PDMS using permeation-driven flows.²²² Eddings et al. confirmed that the fluid flow in a PDMS-based MFD was generated through high gas permeability at the membrane.²²³ The evaporation of water in the polymer walls through permeation resulted in fluid flow due to the excess pressure stored in the compartment.²²⁴ A hybrid PDMS utilizing permeability for fluid flow is shown in Fig. 10. MFD and LOC devices using a vacuum for their passive operation are shown in Fig. 11. Comprehensive developments in vacuum/permeationdriven passive pumping in microfluidics are summarised in Table 7.

Limitations. Due to the limited air diffusion and hydrophobicity of the PDMS material, the flow rates acquired were reduced to nanoliters per second. This could be enhanced by increasing the surface area of the material used.²²³

Critical discussions and limitations

The evolution of new microfluidic tools for genomics, proteomics, and metabolomics is progressing swiftly in research laboratories and will provide the motive for large-scale production. Passive flow methodologies, such as surface-tension-driven flow, capillary-based flow, gravity-driven flow, hydrostatic-pressuredriven flow, and osmosis-driven flow techniques are found to be suitable in assisting the flow without any external sources. Despite the beneficial properties of PDMS that permitted its fast enactment in applied fields, there are several limitations in using the material in biomedical research.²²⁶ The control of fluid flow over space and time with sufficient accuracy was the fundamental challenge in designing MFDs.²²⁷ The initial fabrication of MFDs required clean-room facilities for silicon or glass devices which were eliminated by polymers and elastomers devices. However, PDMS was limited by its ability to withstand high temperature, difficulty in developing complex multi-layered 3D-configured devices, and incompatibility with organic solvents and low molecular weight organic solutes due to their surface chemistry.²²⁸ The usage of inert chemicals and utilization of highthroughput methods for manufacturing and permeability limit the application of PDMS devices in a few cases.²²⁹ Evaporation affects the application of microfluidics in various domains.²³⁰ This could be overridden by maintaining a uniform surface throughout the entire channel area. In pressure-driven techniques, variation in pressure is noted due to the difference in channel length and utilization of different fingers at the inlet.^{119,127} This unbalanced pressure may lead to backflow, followed by clogging or the entire destruction of the device. Hence, a uniform pressure needs to be maintained for a long period. This can be achieved by osmosis-driven MFDs. However, in osmosis-driven MFDs, the osmotic reagent had to be refreshed at regular intervals, which restricted their applications.¹⁴⁵ In addition to that, selection of a suitable membrane is necessary to maintain the pH and to avoid clogging when biological cells or biomolecules are used.¹⁴³ Hence, capillary-based passive flow techniques are used as they depend only on the design and material characteristics of the MFD. On the other hand, in some instances, due to a drop in flow rate, essential pressure prediction at each step decreased sensitivity in capillary-based passive flow techniques.151,165 This could be averted by selection of suitable materials with the ability of spontaneous sample filling in the column.²³¹ Because of this, under many circumstances, gravity-

driven techniques are adopted, but they generate an unstable or decreasing flow rate, which was further eliminated by maintaining an appropriate reservoir volume and proper inlet pressure.^{22,198} Whereas hydrostatic-pressure-driven techniques are limited by the development of Laplace pressure at the air–liquid interface due to the affinity between the liquid, the atmosphere, and the reservoir parameters.²³² Another listed shortcoming was the linear pressure drop with time. These errors could be avoided, if the pressure difference was obtained by varying the altitude of the liquid to the atmospheric interface in the proper way.¹⁹⁷ They could be eliminated by using a vacuum MFD; nevertheless evacuation is necessary to drive the fluid in order to reduce the pressure within the channel. Due to the presence of high pressure initially, the suction of the fluid is higher and gradually decreases as the pressure decreases. Hence a syringe pump is used to maintain a constant flow in the device. This additional requirement can be neglected by the use of simple capillary force.²¹¹ Based on the study performed, the vacuumdriven techniques with complex construction were not suitable for continuous operation due to the evaporation effect and the loss of sample in a few cases.75,208,216 Besides the above-mentioned limitations, these methods found numerous clinical applications, because they use ultra-low volumes of biofluids for processing and can be accomplished quickly and efficiently. **PSC Advances** Article Computer on 23 March 2020. The controlline in the published on 23 March 2022. The controlline in the con

Industrial perspectives

One of the promising types of assistance of microfluidics is found in fast, reliable, and accurate POC diagnostic devices. Detection and diagnostics of communicable diseases can decrease the mortality rate in many developing and less developed countries. As reported by the World Health Organization (WHO), nearly 46% of new tuberculosis case are not detected, causing over 3 million incidences to be missed annually.^{233,234} Also, according to a recent report by WHO, the lack of proper diagnostic capacity is a significant challenge in monitoring effective service coverage. As an example, cholera was estimated to have infected 1.3–4 million people annually and to have caused 21 000–143 000 deaths each year during 2008–2012. But the average annual numbers of cases and deaths reported to WHO were only 313 000 and 5700, respectively. One of the major issues is the lack of diagnostic capacity, which results in the exact burden of the disease being unknown, thus making it difficult to take preventive measures.²³⁵ Although many researchers in the microfluidic domain are focusing on developing diagnosis and detection devices – searching for a few related keywords such as diagnosis, detection, and pathogen detection in LOC, bio-microfluidics, and biomedical microdevices resulted in nearly 3000 papers – many of the products do not end up on the market. One major issue in this regard is transforming common expensive sample delivery systems in laboratories, such as syringe pumps, into passive and low-cost delivery systems to meet the needs of the market in developing and less developed countries. To analyse the status of current commercialized MFDs, we delved into the circle database of uFluidix Inc (http://circle.ufluidix.com). The database includes a list of registered start-ups offering microfluidic

products. Nearly 85% of the analysed start-ups in the diagnostics industry were utilizing a passive method for sample delivery. This clearly emphasizes the importance of passive techniques for industrial sectors.

Conclusion and future directions

Microfluidics is articulated as a multidisciplinary research field that requires basic knowledge in fluidics, micromachining, electromagnetics, materials, and chemistry to find their relevance in the pharmaceutical industry, diagnosis, healthcare, and life science research. LOC is one of the essential applications of microfluidics, and is also a revolutionary tool for many varieties of applications in chemical and biological analyses due to its fascinating advantages (speed, low cost, simplicity, and self-testing) over conventional chemical or laboratory equipment.

Microfluidics covers the science of fluidic behaviours at micro/nanoscales employed in design engineering, simulation, and fabrication of fluidic devices. It is the backbone of biological or biomedical microelectromechanical systems (BioMEMS) and the LOC concept, as most biological analysis involves fluid transport and reaction. MFDs have been operated in inkjet printing, blood analysis, biochemical detection, chemical synthesis, drug screening/delivery, protein analysis, DNA sequencing, and so on. Several different MFDs have been developed with basic structures analogous to macroscale fluidic devices. Such devices include microfluidic valves, microfluidic pumps, and microfluidic mixers. Active devices are usually more expensive, due to their functional and fabrication complexities. However, it has been very challenging to implement these actuation schemes fully at the microscale, owing to the requirements for high voltages, electromagnets, etc. Typically, passive MFDs do not require an external power source, where control is instituted by the energy drawn from the working fluid, or based purely on surface effects, such as surface tension or fluid pressure, with high reliability due to the lack of mechanical wear and tear. Hence, upcoming industrial sectors rely on passive methods to achieve better results in a composed way. Review **Procedures**

Procedures Article in an always article in a diagnos-

Some method for sample Procedure and the sample Procedure and the sample areas are the method in a didning due to the
 CONCINSION and future dir

MFDs offer very repeatable performance, once the underlying phenomena are well understood and characterized. They are well suited to bioMEMS applications, as they can handle several microfluidic manipulation sequences. They are also well suited to the low-cost mass production of disposable MFDs to specifically work with blood. In addition, inexpensive and simple fabrication techniques can promote the use of paperbased MFD in various research fields, such as drug testing and viral detection.

Passive MFDs with high throughput, high flow rate, reduced operation time and easy equipment handling are expected to have profitable outcomes. Therefore, MFDs with passive methods are designed in such a way as to offer a wide range of optimizations that can be performed within the channel and reservoir dimensions for employment to certain specific applications with better flow rates. In the future, device progress will focus on developing new materials for substrates in such a way

as to overcome the drawbacks of currently existing devices. Passive systems cannot maintain constant flow rates. Hence, systems with constant flow rates are expected to be developed as an advantageous method. In addition, a low operation time remains an essential parameter. A reduction in running time can be demonstrated to be the crucial factor on which to focus during upcoming developments. Future work is expected to focus on exploring these listed areas, so that microfluidics can find application in many other fields to satisfy growing demands and needs.

Conflicts of interest

There are no conflicts of interest to declare.

Acknowledgements

The authors would like to thank and acknowledge the Fundamental Research Grant Scheme of the Ministry of Energy, Science, Technology, Environment and Climate Change (MES-TECC), Malaysia (FRGS RDU190108).

References

- 1 E. Lauga, M. Brenner and H. Stone, in Handbook of Experimental Fluid Mechanics, Springer, Heidelberg, 2007, ch. 19, pp. 1219–1240, DOI: 10.1007/978-3-540-30299-5_19.
- 2 H. A. Stone, A. D. Stroock and A. Ajdari, Annu. Rev. Fluid Mech., 2004, 36, 381–411.
- 3 G. M. Whitesides, Nature, 2006, 442, 368–373.
- 4 P. N. Nge, C. I. Rogers and A. T. Woolley, Chem. Rev., 2013, 113, 2550–2583.
- 5 L. Zhu, G. Jiang, S. Wang, C. Wang, Q. Li, H. Yu, Y. Zhou, B. Zhao, H. Huang, W. Xing, K. Mitchelson, J. Cheng, Y. Zhao and Y. Guo, J. Clin. Microbiol., 2010, 48, 3654–3660.
- 6 P. Singh, J. Comput. Appl., 2017, 8, 8–11.
- 7 L. R. Volpatti and A. K. Yetisen, Trends Biotechnol., 2014, 32, 347–350.
- 8 V. Chokkalingam, J. Tel, F. Wimmers, X. Liu, S. Semenov, J. Thiele, C. G. Figdor and W. T. Huck, Lab Chip, 2013, 13, 4740–4744.
- 9 K. K. Jain, Pharmacogenomics, 2000, 1, 289–307.
- 10 Y. Ghallab and W. Badawy, IEEE Circ. Syst. Mag., 2004, 4, 5– 15.
- 11 V. Saggiomo and A. H. Velders, Adv. Sci., 2015, 2, 1500125.
- 12 P. S. Dittrich and A. Manz, Nat. Rev. Drug Discovery, 2006, 5, 210–218.
- 13 S. K. Sia and L. J. Kricka, Lab Chip, 2008, 8, 1982–1983.
- 14 G. J. Kost, N. K. Tran, M. Tuntideelert, S. Kulrattanamaneeporn and N. Peungposop, Am. J. Clin. Pathol., 2006, 126, 513–520.
- 15 M. H. Wu, S. B. Huang and G. B. Lee, Lab Chip, 2010, 10, 939–956.
- 16 L. Y. Wu, D. Di Carlo and L. P. Lee, Biomed. Microdevices, 2008, 10, 197–202.
- 17 L. Kang, B. G. Chung, R. Langer and A. Khademhosseini, Drug Discovery Today, 2008, 13, 1–13.
- 18 C. Kleinstreuer, J. Li and J. Koo, Int. J. Heat Mass Transfer, 2008, 51, 5590–5597.
- 19 Z.-B. Liu, Y. Zhang, J.-J. Yu, A. F.-T. Mak, Y. Li and M. Yang, Sens. Actuators, B, 2010, 143, 776–783.
- 20 Y. C. Toh, T. C. Lim, D. Tai, G. Xiao, D. van Noort and H. Yu, Lab Chip, 2009, 9, 2026–2035.
- 21 L. Yu, M. C. Chen and K. C. Cheung, Lab Chip, 2010, 10, 2424–2432.
- 22 H. E. Abaci, K. Gledhill, Z. Guo, A. M. Christiano and M. L. Shuler, Lab Chip, 2015, 15, 882–888.
- 23 S. R. Khetani, D. R. Berger, K. R. Ballinger, M. D. Davidson, C. Lin and B. R. Ware, J. Lab. Autom., 2015, 20, 216–250.
- 24 J. M. Martel and M. Toner, Sci. Rep., 2013, 3, 3340.
- 25 J. Kr\$uuml\$ger, K. Singh, A. O\$apos\$Neill, C. Jackson, A. Morrison and P. O\$apos\$Brien, J. Micromech. Microeng., 2002, 12, 486–494.
- 26 P. S. Dittrich and P. Schwille, Anal. Chem., 2003, 75, 5767– 5774.
- 27 S.-Y. Yang, S.-K. Hsiung, Y.-C. Hung, C.-M. Chang, T.-L. Liao and G.-B. Lee, Meas. Sci. Technol., 2006, 17, 2001–2009.
- 28 J. C. Baret, O. J. Miller, V. Taly, M. Ryckelynck, A. El-Harrak, L. Frenz, C. Rick, M. L. Samuels, J. B. Hutchison, J. J. Agresti, D. R. Link, D. A. Weitz and A. D. Griffiths, Lab Chip, 2009, 9, 1850–1858. **PSC Advances Article and J. Koo, Jac.** Heat Mass Transfer, 4 R. Bista, Z. Han, P. This article. Now March 2020. Downloaded on 12/2024 9:08:56 PM. This article. Columbished on 24 March 2024 9:08:56 PM. This article is lic
	- 29 A. A. Bhagat, H. Bow, H. W. Hou, S. J. Tan, J. Han and C. T. Lim, Med. Biol. Eng. Comput., 2010, 48, 999–1014.
	- 30 C. W. t. Shields, C. D. Reyes and G. P. Lopez, Lab Chip, 2015, 15, 1230–1249.
	- 31 J. Autebert, B. Coudert, F. C. Bidard, J. Y. Pierga, S. Descroix, L. Malaquin and J. L. Viovy, Methods, 2012, 57, 297–307.
	- 32 X. Zhu, L. Yi Chu, B. H. Chueh, M. Shen, B. Hazarika, N. Phadke and S. Takayama, Analyst, 2004, 129, 1026–1031.
	- 33 W. Gu, X. Zhu, N. Futai and B. S. Cho and S. Takayama, presented in part at the 7th lnternational Conference on Miniaturized Chemical and Blochemlcal Analysts Systems, California USA, 2004.
	- 34 P. J. Hung, P. J. Lee, P. Sabounchi, R. Lin and L. P. Lee, Biotechnol. Bioeng., 2005, 89, 1–8.
	- 35 S. L. Peterson, A. McDonald, P. L. Gourley and D. Y. Sasaki, J. Biomed. Mater. Res., Part A, 2005, 72, 10–18.
	- 36 P. Lee, R. Lin, J. Moon and L. P. Lee, Biomed. Microdevices, 2006, 8, 35–41.
	- 37 R. Gomez-Sjoberg, A. A. Leyrat, D. M. Pirone, C. S. Chen and S. R. Quake, Anal. Chem., 2007, 79, 8557–8563.
	- 38 S. M. Ong, C. Zhang, Y. C. Toh, S. H. Kim, H. L. Foo, C. H. Tan, D. van Noort, S. Park and H. Yu, Biomaterials, 2008, 29, 3237–3244.
	- 39 V. Lecault, M. Vaninsberghe, S. Sekulovic, D. J. Knapp, S. Wohrer, W. Bowden, F. Viel, T. McLaughlin, A. Jarandehei, M. Miller, D. Falconnet, A. K. White, D. G. Kent, M. R. Copley, F. Taghipour, C. J. Eaves, R. K. Humphries, J. M. Piret and C. L. Hansen, Nat. Methods, 2011, 8, 581–586.
	- 40 M. Mehling and S. Tay, Curr. Opin. Biotechnol., 2014, 25, 95– 102.
- 41 R. Sista, Z. Hua, P. Thwar, A. Sudarsan, V. Srinivasan, A. Eckhardt, M. Pollack and V. Pamula, Lab Chip, 2008, 8, 2091–2104.
- 42 F. B. Myers and L. P. Lee, Lab Chip, 2008, 8, 2015–2031.
- 43 E. K. Sackmann, A. L. Fulton and D. J. Beebe, Nature, 2014, 507, 181–189.
- 44 D. B. Weibel and G. M. Whitesides, Curr. Opin. Chem. Biol., 2006, 10, 584–591.
- 45 P. Gravesen, J. Branebjerg and O. S. Jensen, J. Micromech. Microeng., 1993, 3, 168–182.
- 46 H. A. Stone and S. Kim, AIChE J., 2001, 47, 1250–1254.
- 47 J. C. McDonald, D. C. Duffy, J. R. Anderson, D. T. Chiu, H. Wu, O. J. A. Schueller and G. M. Whitesides, Electrophoresis, 2000, 21, 27–40.
- 48 T. Fujii, Microelectron. Eng., 2002, 61–62, 907–914.
- 49 J. C. McDonald and G. M. Whitesides, Acc. Chem. Res., 2002, 35, 491–499.
- 50 J. Kuncova-Kallio and P. J. Kallio, Conf. Proc. IEEE Eng. Med. Biol. Soc., 2006, 1, 2486–2489.
- 51 J. Zhou, A. V. Ellis and N. H. Voelcker, Electrophoresis, 2010, 31, 2–16.
- 52 T. C. Merkel, V. I. Bondar, K. Nagai, B. D. Freeman and I. Pinnau, J. Polym. Sci., 2000, 38, 415–434.
- 53 D. J. Beebe, G. A. Mensing and G. M. Walker, Annu. Rev. Biomed. Eng., 2002, 4, 261–286.
- 54 G. S. Fiorini and D. T. Chiu, Biotechniques, 2005, 38, 429– 446.
- 55 J.-H. Tsai and L. Lin, Sens. Actuators, A, 2002, 97–98, 665– 671.
- 56 M. M. Teymoori and E. Abbaspour-Sani, Sens. Actuators, A, 2005, 117, 222–229.
- 57 C. K. Byun, K. Abi-Samra, Y. K. Cho and S. Takayama, Electrophoresis, 2014, 35, 245–257.
- 58 P. H. Huang, N. Nama, Z. Mao, P. Li, J. Rufo, Y. Chen, Y. Xie, C. H. Wei, L. Wang and T. J. Huang, Lab Chip, 2014, 14, 4319–4323.
- 59 A. Terray, J. Oakey and D. W. Marr, Science, 2002, 296, 1841– 1844.
- 60 T. Vestad, D. W. M. Marr and J. Oakey, J. Micromech. Microeng., 2004, 14, 1503–1506.
- 61 H.-P. Chou, M. A. Unger and S. R. Quake, Biomed. Microdevices, 2001, 3, 323–330.
- 62 V. Studer, A. Pepin, Y. Chen and A. Ajdari, Analyst, 2004, 129, 944–949.
- 63 C.-Y. Lee, G.-B. Lee, J.-L. Lin, F.-C. Huang and C.-S. Liao, J. Micromech. Microeng., 2005, 15, 1215–1223.
- 64 M. G. Pollack, R. B. Fair and A. D. Shenderov, Appl. Phys. Lett., 2000, 77, 1725–1726.
- 65 X. Wang, C. Cheng, S. Wang and S. Liu, Microfluid. Nanofluid., 2009, 6, 145.
- 66 C. Sung Kwon, M. Hyejin and K. Chang-Jin, J. Microelectromech. Syst., 2003, 12, 70–80.
- 67 F. Xia, S. Tadigadapa and Q. M. Zhang, Sens. Actuators, A, 2006, 125, 346–352.
- 68 M. Shen, L. Dovat and M. A. M. Gijs, Sens. Actuators, B, 2011, 154, 52–58.
- 69 M. E. Harmon, M. Tang and C. W. Frank, Polymer, 2003, 44, 4547–4556.
- 70 J. Berthier, P. Dubois, P. Clementz, P. Claustre, C. Peponnet and Y. Fouillet, Sens. Actuators, A, 2007, 134, 471–479.
- 71 D. H. Jun, W. Y. Sim and S. S. Yang, Sens. Actuators, A, 2007, 139, 210–215.
- 72 D. T. Wong, J. Am. Dent. Assoc., 2006, 137, 313–321.
- 73 S. Upadhyaya and P. R. Selvaganapathy, Lab Chip, 2010, 10, 341–348.
- 74 L. Gervais, N. de Rooij and E. Delamarche, Adv. Mater., 2011, 23, H151–H176.
- 75 K. Hosokawa, K. Sato, N. Ichikawa and M. Maeda, Lab Chip, 2004, 4, 181–185.
- 76 S. K. Sia and G. M. Whitesides, Electrophoresis, 2003, 24, 3563–3576.
- 77 T. Bayraktar and S. B. Pidugu, Int. J. Heat Mass Transfer, 2006, 49, 815–824.
- 78 S. Haeberle and R. Zengerle, Lab Chip, 2007, 7, 1094–1110.
- 79 E. W. Young and D. J. Beebe, Chem. Soc. Rev., 2010, 39, 1036–1048.
- 80 C. H. Ahn and J.-W. Choi, in Springer Handbook of Nanotechnology, Springer Handbook, 2010, pp. 503–530, DOI: 10.1007/978-3-642-02525-9_18.
- 81 W. Su, X. Gao, L. Jiang and J. Qin, J. Chromatogr. A, 2015, 1377, 13–26.
- 82 S. Tripathi, Y. V. B. Varun Kumar, A. Prabhakar, S. S. Joshi and A. Agrawal, J. Micromech. Microeng., 2015, 25, 083001.
- 83 V. Narayanamurthy, S. Nagarajan, A. a. Y. Firus Khan, F. Samsuri and T. M. Sridhar, Anal. Methods, 2017, 9, 3751–3772.
- 84 J. H. W. Guo and W. van der Wijngaart, *presented in part at* the 20th International Conference on Miniaturized Systems for Chemistry and Life Sciences, Ireland, 2016.
- 85 W. Guo, J. Hansson and W. van der Wijngaart, Microsyst. Nanoeng., 2018, 4, 2.
- 86 W. Guo, J. Hansson and W. van der Wijngaart, presented in part at the 2017 IEEE 30th International Conference on Micro Electro Mechanical Systems (MEMS), Las Vegas, NV, USA, Jan. 2017, 2017, vol. 22–26.
- 87 Microfluidics Market by Application (Genomics, Proteomics, Capillary Electrophoresis, IVD (POC, Clinical Diagnostics), Drug Delivery, Microreactor, Lab Tests), Component (Chips, Pump, Needle), Material (Polymer, Glass, Silicon) - Global Forecast to 2023, https:// www.marketsandmarkets.com/Market-Reports/

microfluidics-market-1305.html?

lw6jRwrmW0UWaEBWePRfCRoCw3MQAvD_BwE, 2019.

- 88 G. Gabrielse, X. Fei, L. A. Orozco, R. L. Tjoelker, J. Haas, H. Kalinowsky, T. A. Trainor and W. Kells, Phys. Rev. Lett., 1990, 65, 1317–1320.
- 89 S. Yd and S. C. Maroo, Langmuir, 2016, 32, 8593–8597.
- 90 V. B. Makhijani, A. J. Reich, A. Puntambekar, C. Hong and C. Ahn, TechConnect Briefs, 2001, 1, 266–269.
- 91 G. Walker and D. J. Beebe, Lab Chip, 2002, 2, 131–134.
- 92 G. M. Walker and D. J. Beebe, Lab Chip, 2002, 2, 57–61.
- 93 C. Chien-Fu, K. Shih-Chi, C. Chin-Chou and T. Fan-Gang, presented in part at the Sixteenth Annual International Conference on Micro Electro Mechanical Systems, 2003, MEMS-03 Kyoto, IEEE, Kyoto, Japan, Japan, 2003. **Second on 24**
 Second on 23
 Second on 23
 Second on 24 Access Articles. Published on 24
 Second on 24 Access Article is licensed under a presed unit on 24 Access Article is licensed under a presed unit on 24 Acces
	- 94 T. Ward, M. Faivre, M. Abkarian and H. A. Stone, Electrophoresis, 2005, 26, 3716–3724.
	- 95 Y. C. Tan, J. S. Fisher, A. I. Lee, V. Cristini and A. P. Lee, Lab Chip, 2004, 4, 292–298.
	- 96 Y. Yang and Y. C. Liang, J. Power Sources, 2007, 165, 185– 195.
	- 97 E. Berthier and D. J. Beebe, Lab Chip, 2007, 7, 1475–1478.
	- 98 I. Meyvantsson, J. W. Warrick, S. Hayes, A. Skoien and D. J. Beebe, Lab Chip, 2008, 8, 717–724.
	- 99 J. Ju, J. Y. Park, K. C. Kim, H. Kim, E. Berthier, D. J. Beebe and S.-H. Lee, J. Micromech. Microeng., 2008, 18, 087002.
	- 100 Y. Du, J. Shim, M. Vidula, M. J. Hancock, E. Lo, B. G. Chung, J. T. Borenstein, M. Khabiry, D. M. Cropek and A. Khademhosseini, Lab Chip, 2009, 9, 761–767.
	- 101 I. J. Chen, E. C. Eckstein and E. Lindner, Lab Chip, 2009, 9, 107–114.
	- 102 P. J. Resto, B. J. Mogen, E. Berthier and J. C. Williams, Lab Chip, 2010, 10, 23–26.
	- 103 P. J. Resto, B. Mogen, F. Wu, E. Berthier, D. Beebe and J. Williams, J. Visualized Exp., 2009, e1329.
	- 104 I. J. Chen and E. Lindner, Anal. Chem., 2009, 81, 9955–9960.
	- 105 A. L. McPherson and G. M. Walker, Microfluid. Nanofluid., 2010, 9, 897–904.
	- 106 J. P. Puccinelli, X. Su and D. J. Beebe, JALA Charlottesv Va, 2010, 15, 25–32.
	- 107 B. G. Chung and J. Choo, Electrophoresis, 2010, 31, 3014– 3027.
	- 108 G. Lin and A. P. Lee, Ann. N. Y. Acad. Sci., 2010, 1190, 186– 192.
	- 109 E. Berthier, J. Warrick, B. Casavant and D. J. Beebe, Lab Chip, 2011, 11, 2060–2065.
	- 110 P. J. Resto, E. Berthier, D. J. Beebe and J. C. Williams, Lab Chip, 2012, 12, 2221–2228.
	- 111 J. T. Kuo, C. Li and E. Meng, Conf. Proc. IEEE Eng. Med. Biol. Soc., 2014, 2014, 4415–4418.
	- 112 T. E. de Groot, K. S. Veserat, E. Berthier, D. J. Beebe and A. B. Theberge, Lab Chip, 2016, 16, 334–344.
	- 113 K. Javadi, H. Moezzi-Rafie, V. Goodarzi-Ardakani, A. Javadi and R. Miller, Colloids Surf., A, 2017, 518, 30–45.
	- 114 K. Iwai, R. D. Sochol and L. Lin, presented in part at the 2011 IEEE 24th International Conference on Micro Electro Mechanical Systems, Cancun, Mexico, 2011.
	- 115 H. Jönsson, Microfluidics for lab-on-a-chip applications, MSc thesis, Lund University, 2004.
	- 116 R. H. Liu, M. A. Stremler, K. V. Sharp, M. G. Olsen, J. G. Santiago, R. J. Adrian, H. Aref and D. J. Beebe, J. Microelectromech. Syst., 2000, 9, 190–197.
	- 117 C. H. Ahn, A. Puntambekar, S. M. Lee, H. J. Cho and C.-C. Hong, presented in part at the Micro Total Analysis Systems 2000, 2000.
	- 118 N. L. Jeon, D. T. Chiu, C. J. Wargo, H. Wu, I. S. Choi, J. R. Anderson and G. M. Whitesides, Biomed. Microdevices, 2002, 4, 117–121.

gclid=CjwKCAiArK_fBRABEiwA0gOOc_

eZ1aIgVylO7GQPYakcbg9F1lH6zEf-

- 119 B. M. Rush, K. D. Dorfman, H. Brenner and S. Kim, Ind. Eng. Chem. Res., 2002, 41, 4652–4662.
- 120 J. Moorthy and D. J. Beebe, Lab Chip, 2003, 3, 62–66.
- 121 Y. Hu, C. Werner and D. Li, J. Fluids Eng., 2003, 125, 871– 879.
- 122 C. o.-K. Chen and C.-C. Cho, Chem. Eng. Sci., 2008, 63, 3081–3087.
- 123 H. Jiang, X. Weng and D. Li, Microfluid. Nanofluid., 2010, 10, 941–964.
- 124 K. Hattori, S. Sugiura and T. Kanamori, J. Lab. Autom., 2013, 18, 437–445.
- 125 N. Davey and A. Neild, J. Colloid Interface Sci., 2011, 357, 534–540.
- 126 J. D. Tice, A. V. Desai, T. A. Bassett, C. A. Apblett and P. J. A. Kenis, RSC Adv., 2014, 4, 51593–51602.
- 127 K. Iwai, K. C. Shih, X. Lin, T. A. Brubaker, R. D. Sochol and L. Lin, Lab Chip, 2014, 14, 3790–3799.
- 128 L. Xu, H. Lee and K. W. Oh, Microfluid. Nanofluid., 2014, 17, 745–750.
- 129 T. Kokalj, Y. Park, M. Vencelj, M. Jenko and L. P. Lee, Lab Chip, 2014, 14, 4329–4333.
- 130 G. S. Jeong, J. Oh, S. B. Kim, M. R. Dokmeci, H. Bae, S. H. Lee and A. Khademhosseini, Lab Chip, 2014, 14, 4213–4219.
- 131 V. Tandon, W. S. Kang, T. A. Robbins, A. J. Spencer, E. S. Kim, M. J. McKenna, S. G. Kujawa, J. Fiering, E. E. Pararas, M. J. Mescher, W. F. Sewell and J. T. Borenstein, Lab Chip, 2016, 16, 829–846. **PSC Advances**
 SCONDING ACCESS ARTICLE IN ACCESS ARTICLE IN A SCONS ARTICLE IS A SCONS ARTICLE IN A SCONS ARTICLE IS A SCONS
	- 132 S. Lee, H. Kim, W. Lee and J. Kim, Micro and Nano Systems Letters, 2018, 6, 1.
	- 133 E. S. Kim, E. Gustenhoven, M. J. Mescher, E. E. Pararas, K. A. Smith, A. J. Spencer, V. Tandon, J. T. Borenstein and J. Fiering, Lab Chip, 2014, 14, 710–721.
	- 134 T. Satoh, G. Narazaki, R. Sugita, H. Kobayashi, S. Sugiura and T. Kanamori, Lab Chip, 2016, 16, 2339–2348.
	- 135 X. Zhang, X. Wang, K. Chen, J. Cheng, N. Xiang and Z. Ni, RSC Adv., 2016, 6, 31639–31646.
	- 136 B. U. Moon, N. Abbasi, S. G. Jones, D. K. Hwang and S. S. Tsai, Anal. Chem., 2016, 88, 3982–3989.
	- 137 H. Ryu, K. Choi, Y. Qu, T. Kwon, J. S. Lee and J. Han, Anal. Chem., 2017, 89, 5549–5556.
	- 138 A. M. Nightingale, G. W. Evans, P. Xu, B. J. Kim, S. U. Hassan and X. Niu, Lab Chip, 2017, 17, 1149–1157.
	- 139 F. Dal Dosso, T. Kokalj, J. Belotserkovsky, D. Spasic and J. Lammertyn, Biomed. Microdevices, 2018, 20, 44.
	- 140 B. Liu, M. Li, B. Tian, X. Yang and J. Yang, Microfluid. Nanofluid., 2018, 22, 94.
	- 141 M. Boyd-Moss, S. Baratchi, M. Di Venere and K. Khoshmanesh, Lab Chip, 2016, 16, 3177–3192.
	- 142 C. J. C. Biscombe, Angew. Chem., Int. Ed., 2017, 56, 8338– 8340.
	- 143 B. R. Bruhn, T. B. Schroeder, S. Li, Y. N. Billeh, K. W. Wang and M. Mayer, PLoS One, 2014, 9, e91350.
	- 144 B. T. Good, C. N. Bowman and R. H. Davis, J. Colloid Interface Sci., 2007, 305, 239–249.
	- 145 Z. R. Xu, C. G. Yang, C. H. Liu, Z. Zhou, J. Fang and J. H. Wang, Talanta, 2010, 80, 1088–1093.
- 146 J. Y. Park, S. K. Kim, D. H. Woo, E. J. Lee, J. H. Kim and S. H. Lee, Stem Cells, 2009, 27, 2646–2654.
- 147 A. L. Paguirigan and D. J. Beebe, Integr. Biol., 2009, 1, 182– 195.
- 148 J. Y. Park, S. J. Yoo, L. Patel, S. H. Lee and S. H. Lee, Biorheology, 2010, 47, 165–178.
- 149 S.-H. Kim, K. Kim, M. Go and J. Y. Park, J. Micromech. Microeng., 2018, 28, 125005.
- 150 S. Herrlich, S. Spieth, S. Messner and R. Zengerle, Adv. Drug Delivery Rev., 2012, 64, 1617–1627.
- 151 D. Juncker, H. Schmid, U. Drechsler, H. Wolf, M. Wolf, B. Michel, N. de Rooij and E. Delamarche, Anal. Chem., 2002, 74, 6139–6144.
- 152 K. Hosokawa and M. Maeda, IEEJ Transactions on Sensors and Micromachines, 2003, 123, 23–24.
- 153 S.-J. Kim, Y. B. Shin, D.-S. Lee, H. Yang, K. Kim, S. H. Park and Y. T. Kim, presented in part at the 7th lnternational Conference on Miniaturized Chemical and Blochemlcal Analysts Systems, California USA, 2003.
- 154 N. Ichikawa, K. Hosokawa and R. Maeda, J. Colloid Interface Sci., 2004, 280, 155–164.
- 155 M. Zimmermann, H. Schmid, P. Hunziker and E. Delamarche, Lab Chip, 2007, 7, 119–125.
- 156 J. W. Suk and J.-H. Cho, J. Micromech. Microeng., 2007, 17, N11–N15.
- 157 Y. Zhu and K. Petkovic-Duran, Microfluid. Nanofluid., 2009, 8, 275–282.
- 158 N. S. Lynn and D. S. Dandy, Lab Chip, 2009, 9, 3422–3429.
- 159 L. Gervais and E. Delamarche, Lab Chip, 2009, 9, 3330– 3337.
- 160 S. Mukhopadhyay, S. S. Roy, A. Mathur, M. Tweedie and J. A. McLaughlin, J. Micromech. Microeng., 2010, 20, 055018.
- 161 A. H. Ng, U. Uddayasankar and A. R. Wheeler, Anal. Bioanal. Chem., 2010, 397, 991–1007.
- 162 Y. C. Kim, S.-H. Kim, D. Kim, S.-J. Park and J.-K. Park, Sens. Actuators, B, 2010, 145, 861–868.
- 163 F. R. de Souza, G. L. Alves and W. K. Coltro, Anal. Chem., 2012, 84, 9002–9007.
- 164 T. Horiuchi, T. Miura, Y. Iwasaki, M. Seyama, S. Inoue, J. Takahashi, T. Haga and E. Tamechika, Sensors, 2012, 12, 7095–7108.
- 165 S. J. Kim, S. Paczesny, S. Takayama and K. Kurabayashi, Lab Chip, 2013, 13, 2091–2098.
- 166 K. Kistrup, C. E. Poulsen, P. F. Østergaard, K. B. Haugshøj, R. Taboryski, A. Wolff and M. F. Hansen, J. Micromech. Microeng., 2014, 24, 125007.
- 167 J. Berthier, K. A. Brakke, D. Gosselin, A. G. Bourdat, G. Nonglaton, N. Villard, G. Laffite, F. Boizot, G. Costa and G. Delapierre, Microfluid. Nanofluid., 2014, 18, 919-929.
- 168 H. Madadi, J. Casals-Terre and M. Mohammadi, Biofabrication, 2015, 7, 025007.
- 169 C. Nie, A. J. Frijns, R. Mandamparambil and J. M. den Toonder, Biomed. Microdevices, 2015, 17, 47.
- 170 S. Mukhopadhyay, J. P. Banerjee, S. S. Roy, S. K. Metya, M. Tweedie and J. A. McLaughlin, Surf. Rev. Lett., 2017, 24, 1750041.
- 171 M. Huet, M. Cubizolles and A. Buhot, Biosens. Bioelectron., 2017, 93, 110–117.
- 172 F. Bunge, S. van den Driesche and M. J. Vellekoop, Microfluid. Nanofluid., 2016, 20, 95.
- 173 T. Wu, Z. Luo, W. Ding, Z. Cheng and L. He, Microfluid. Nanofluid., 2017, 21, 129.
- 174 Y. Zhai, A. Wang, D. Koh, P. Schneider and K. W. Oh, Lab Chip, 2018, 18, 276–284.
- 175 J. Xie, H. Su, J. Liao and J. Liu, Microfluid. Nanofluid., 2017, 21, 106.
- 176 N. Vasilakis, K. I. Papadimitriou, H. Morgan and T. Prodromakis, Microfluid. Nanofluid., 2017, 21.
- 177 T. Akyazi, N. Gil-González, L. Basabe-Desmonts, E. Castaño, M. C. Morant-Miñana and F. Benito-Lopez, Sens. Actuators, B, 2017, 247, 114–123.
- 178 J.-P. Frimat, B. Schurink and R. Luttge, J. Vac. Sci. Technol., B: Nanotechnol. Microelectron.: Mater., Process., Meas., Phenom., 2017, 35, 06GA01.
- 179 L. Mei, M. Jin, S. Xie, Z. Yan, X. Wang, G. Zhou, A. van den Berg and L. Shui, Lab Chip, 2018, 18, 2806–2815.
- 180 B. Kim, S. Oh, S. Shin, S. G. Yim, S. Y. Yang, Y. K. Hahn and S. Choi, Anal. Chem., 2018, 90, 8254–8260.
- 181 E. Moonen, R. Luttge and J.-P. Frimat, Microelectron. Eng., 2018, 197, 1–7.
- 182 H. Tachibana, M. Saito, K. Tsuji, K. Yamanaka, L. Q. Hoa and E. Tamiya, Sens. Actuators, B, 2015, 206, 303–310.
- 183 M. M. Aeinehvand, F. Ibrahim, S. W. Harun, W. Al-Faqheri, T. H. Thio, A. Kazemzadeh and M. Madou, Lab Chip, 2014, 14, 988–997.
- 184 A. Olanrewaju, M. Beaugrand, M. Yafia and D. Juncker, Lab Chip, 2018, 18, 2323–2347.
- 185 A.-J. Mäki, S. Hemmilä, J. Hirvonen, N. N. Girish, J. Kreutzer, J. Hyttinen and P. Kallio, J. Fluids Eng., 2015, 137, 21105.
- 186 B. S. Cho, T. G. Schuster, X. Zhu, D. Chang, G. D. Smith and S. Takayama, Anal. Chem., 2003, 75, 1671–1675.
- 187 R. S. Suh, N. Phadke, D. A. Ohl, S. Takayama and G. D. Smith, Hum. Reprod. Update, 2003, 9, 451–461.
- 188 H. Yamada, Y. Yoshida and N. Terada, Jpn. J. Appl. Phys., 2005, 44, 8739–8741.
- 189 D. Huh, J. H. Bahng, Y. Ling, H. H. Wei, O. D. Kripfgans, J. B. Fowlkes, J. B. Grotberg and S. Takayama, Anal. Chem., 2007, 79, 1369–1376.
- 190 P. J. Lee, N. Ghorashian, T. A. Gaige and P. J. Hung, JALA Charlottesv Va, 2007, 12, 363–367.
- 191 K. Zhang, Q. Liang, S. Ma, T. He, X. Ai, P. Hu, Y. Wang and G. Luo, Microfluid. Nanofluid., 2010, 9, 995-1001.
- 192 J. H. Sung, C. Kam and M. L. Shuler, Lab Chip, 2010, 10, 446–455.
- 193 M. B. Esch, J. M. Prot, Y. I. Wang, P. Miller, J. R. Llamas-Vidales, B. A. Naughton, D. R. Applegate and M. L. Shuler, Lab Chip, 2015, 15, 2269–2277.
- 194 D. Jin, B. Deng, J. X. Li, W. Cai, L. Tu, J. Chen, Q. Wu and W. H. Wang, Biomicrofluidics, 2015, 9, 014101.
- 195 J. James, M. Sushmitha, R. Premkumar, V. Narayanamurthy and R. Kalpana, presented in part at the 2017 International

conference on Microelectronic Devices, Circuits and Systems (ICMDCS), Vellore, India, 2017.

- 196 V. Narayanamurthy, T. Lee, A. a. Khan, F. Samsuri, K. Mohamed, H. Hamzah and M. Baharom, Fluids, 2018, 3, 51.
- 197 S.-J. Kim, X. Zhu and S. Takayama, in Microtechnology for Cell Manipulation and Sorting, Springer, 2017, pp. 175– 192, DOI: 10.1007/978-3-319-44139-9_6.
- 198 D.-b. Seo, Y. Agca, Z. C. Feng and J. K. Critser, Microfluid. Nanofluid., 2007, 3, 561-570.
- 199 S. M. Knowlton, M. Sadasivam and S. Tasoglu, Trends Biotechnol., 2015, 33, 221–229.
- 200 P. J. Shah, M. Dimaki and W. E. Svendsen, presented in part at the TRANSDUCERS 2009 - 2009 International Solid-State Sensors, Actuators and Microsystems Conference, Denver, CO, USA, 2009. **Review**

171 M. Hues, M. Cabizolies and A. Bubie, Biosetterroot, conference on Microscheronic Reviews, Creatis and System

1822 March 2020. The Licensed under a creation of the Commons Articles. The A. B. When \bar{Y} , E.
	- 201 Benefits of Water Therapy, https://www.friendshiphaven.org/ benefits-of-water-therapy/.
	- 202 B. H. Weigl, R. Bardell, T. Schulte and C. Williams, presented in part at the Micro Total Analysis Systems 2000, 2000.
	- 203 B. H. Weigl, R. L. Bardell, N. Kesler and C. J. Morris, Fresenius. J. Anal. Chem., 2014, 371, 97–105.
	- 204 M. Marimuthu and S. Kim, Anal. Biochem., 2013, 437, 161– 163.
	- 205 M. Komeya, K. Hayashi, H. Nakamura, H. Yamanaka, H. Sanjo, K. Kojima, T. Sato, M. Yao, H. Kimura, T. Fujii and T. Ogawa, Sci. Rep., 2017, 7, 15459.
	- 206 W. Wu, Analyst, 2018, 143, 4819–4835.
	- 207 Q. Song, J. Sun, Y. Mu, Y. Xu, Q. Zhu and Q. Jin, Sens. Actuators, B, 2018, 256, 1122–1130.
	- 208 J. Monahan, A. A. Gewirth and R. G. Nuzzo, Anal. Chem., 2001, 73, 3193–3197.
	- 209 K. Hosokawa, M. Omata, K. Sato and M. Maeda, Lab Chip, 2006, 6, 236–241.
	- 210 I. K. Dimov, L. Basabe-Desmonts, J. L. Garcia-Cordero, B. M. Ross, Y. Park, A. J. Ricco and L. P. Lee, Lab Chip, 2011, 11, 845–850.
	- 211 D. Y. Liang, A. M. Tentori, I. K. Dimov and L. P. Lee, Biomicrofluidics, 2011, 5, 24108.
	- 212 G. Li, Y. Luo, Q. Chen, L. Liao and J. Zhao, Biomicrofluidics, 2012, 6, 14118–1411816.
	- 213 C. G. Li, M. Dangol, C. Y. Lee, M. Jang and H. Jung, Lab Chip, 2015, 15, 382–390.
	- 214 L. Xu, H. Lee, D. Jetta and K. W. Oh, Lab Chip, 2015, 15, 3962–3979.
	- 215 C. Li, J. Xu and B. Ma, Microfluid. Nanofluid., 2014, 18, 1067–1073.
	- 216 D. Agustini, M. F. Bergamini and L. H. Marcolino-Junior, Anal. Chim. Acta, 2017, 951, 108–115.
	- 217 B. Liu, D. Koh, A. Wang, P. Schneider and K. W. Oh, Microsyst. Technol., 2017, 24, 2035–2043.
	- 218 Y. Li, Y. Jiang, K. Wang and W. Wu, Anal. Chem., 2018, 90, 11925–11932.
	- 219 Y. Liu and G. Li, Sci. Rep., 2018, 8, 13664.
	- 220 J. Warrick, I. Meyvantsson, J. Ju and D. J. Beebe, Lab Chip, 2007, 7, 316–321.
- 221 E. Verneuil, A. Buguin and P. Silberzan, Europhys. Lett., 2004, 68, 412–418.
- 222 G. C. Randall and P. S. Doyle, Proc. Natl. Acad. Sci. U. S. A., 2005, 102, 10813–10818.
- 223 M. A. Eddings and B. K. Gale, J. Micromech. Microeng., 2006, 16, 2396–2402.
- 224 D. B. Weibel, A. C. Siegel, A. Lee, A. H. George and G. M. Whitesides, Lab Chip, 2007, 7, 1832–1836.
- 225 M. Johnson, G. Liddiard, M. Eddings and B. Gale, J. Micromech. Microeng., 2009, 19, 095011.
- 226 D. T. Chiu, A. J. deMello, D. Di Carlo, P. S. Doyle, C. Hansen, R. M. Maceiczyk and R. C. R. Wootton, Chem, 2017, 2, 201– 223.
- 227 D. C. Leslie, C. J. Easley, E. Seker, J. M. Karlinsey, M. Utz, M. R. Begley and J. P. Landers, Nat. Phys., 2009, 5, 231–235.
- 228 Y. T. Atalay, S. Vermeir, D. Witters, N. Vergauwe, B. Verbruggen, P. Verboven, B. M. Nicolaï and J. Lammertyn, Trends Food Sci. Technol., 2011, 22, 386–404.
- 229 M.-C. Bélanger and Y. Marois, J. Biomed. Mater. Res., 2001, 58, 467–477.
- 230 S. Kachel, Y. Zhou, P. Scharfer, C. Vrancic, W. Petrich and W. Schabel, Lab Chip, 2014, 14, 771–778.
- 231 M. Hitzbleck and E. Delamarche, Micromachines, 2013, 4, 1– 8.
- 232 P. Shah, X. Zhu, C. Chen, Y. Hu and C. Z. Li, Biomed. Microdevices, 2014, 16, 35–41.
- 233 Global tuberculosis report 2014, http://www.who.int/iris/ handle/10665/137094, accessed March, 2019.
- 234 R. McNerney, Diagnostics, 2015, 5, 200–209.
- 235 W. H. Organization, World health statistics 2016: monitoring health for the SDGs sustainable development goals, World Health Organization, 2016. **PSC Advances** America Articles. Published on 23 March 2021. Downloaded on 12/2024 9:08:56 PM. This article is liken to the energy and 22 March 2024 9:06, PM. This article is liken to the energy and 23 March 2021 March 202