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Introduction

Microbial surface charge impacts a cell's interaction with its local environment, including other cells, ions and particles. The exposed carboxyl and amine groups from bacterial peptidoglycans renders most negatively charged. This negative charge is crucial for nutrient, metabolite, and ionic interactions within the bacteria as well as their transport into the cell.^{1–4} Moreover, surface charge and hydrophobicity are predictive of bacterial adhesion, which is critical for host invasion by pathogens and biofilm formation.⁵ Importantly, surface charge has also been linked to the virulence of different bacterial strains; as an example, *Mycobacterium tuberculosis* strains, with differential virulence have divergent surface charges.¹ Finally, this physical property can be used to separate microbes using capillary electrokinetics.⁶

Zeta potential characterization using commercial microfluidic chips†

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Surface charge is a critical feature of microbes that affects their interactions with other cells and their environment. Because bacterial surface charge is difficult to measure directly, it is typically indirectly inferred through zeta potential measurements. Existing tools to perform such characterization are either costly and ill-suited for non-spherical samples or rely on microfluidic techniques requiring expensive fabrication equipment or specialized facilities. Here, we report the application of commercially available PMMA microfluidic chips and open-source data analysis workflows for facile electrokinetic characterization of particles and cells after prior zeta potential measurement with a Zetasizer for calibration. Our workflows eliminate the need for microchannel fabrication, increase measurement reproducibility, and make zeta potential measurements more accessible. This novel methodology was tested with functionalized 1 µm and 2 µm polystyrene beads as well as *Escherichia coli* MG1655 strain. Measured zeta potentials for these samples were in agreement with literature values obtained by conventional measurement methods. Taken together, our data demonstrate the power of this workflow to broadly enable critical measurements of particle and bacterial zeta potential for numerous applications.

Therefore, quantifying microbial surface charge provides critical phenotypic information.⁷

Unfortunately, bacterial surface charge typically cannot be directly measured but must instead be inferred through zeta potential, ζ . When charged particles are suspended in an electrolyte solution, counter ions from the bulk form a thin electrical double layer (EDL) at the solid-liquid interface.^{8,9} The ζ is the electric potential at this interface between the inner and outer layers of the EDL.^{10,11} The inner layer contains the fixed Stern layer and an almost immobile shear layer, while the outer layer (the diffusive layer) is comprised of mobile ions in proximity to the surface due to electrostatic forces. The ζ of a particle in solution is therefore defined by both its surface characteristics as well as the composition of the solution it is in (e.g. pH, ionic strength and electrical conductivity^{7,12}). This influence of the environment can make measuring the ζ challenging and can lead irreproducibility.^{7,12}

Since ζ is an important method for inferring surface charge, significant effort has been devoted to measuring it. Typically, a capillary cell is used with electrodes at both ends where a potential is applied.^{7,12} Particles move towards the electrode with opposite charge while their velocity is recorded. Such commercial instruments typically use dynamic light scattering (DLS) to extrapolate ζ and has enabled researchers to rapidly measure this parameter. However, these systems also have significant limitations; they are very costly, utilize

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[†] Electronic supplementary information (ESI) available: Microparticle information determined in this study with the Zetasizer Ultra and with electrokinetics results as well as reservoir caps modification procedure, outlier removal discussion and experimental flow chart. See DOI: https://doi.org/10.1039/d3lc00825h

DLS and must assume spherical particles for its calculations, and are therefore not suited for non-spherical particles (such as many bacteria).^{13–16}

To enable consistent, reproducible ζ measurements with a broader range of samples and at lower cost, many research groups have leveraged microfluidics. Lapizco-Encinas and coworkers have specialized in using polydimethylsiloxane (PDMS) microchannels for electrokinetic characterization of particles and cells.¹⁷ These chips have been used to measure the non-linear electrophoretic mobility of cells and particles using particle tracking velocimetry (PTV).¹⁸⁻²¹ However, the application of in-house fabricated PDMS molds requires specialized expertise and cleanroom access, limiting the technique to labs with such capabilities. Additionally, the ζ of the microchannel must be measured in the media used prior to experiments through current monitoring, a method limited to solutions with low electrical conductivities.²² More recently, some have moved to polymethyl methacrylate (PMMA) microchannels, but this method still requires expensive computer numerical control (CNC) machines and fabrication expertise.^{23,24} Further, all current methods lack electrode positioning and require tedious precise microchannel conditioning. Thus, the field will benefit from new solutions that circumvent these costly fabrication and measurement limitations.

Here we report the use of commercial PMMA microfluidic chips to perform electrokinetic characterization of particles and bacteria, negating the need for microchannel microfabrication. The method employed herein results in increased measurement reproducibility and is more accessible (in terms of both cost and expertise required) than previous techniques. All components were developed to enable broad adoption, combining commercial platforms with open-source software. This methodology was tested with functionalized 1 μ m and 2 μ m polystyrene beads as well as a prevalent strain of *Escherichia coli*, MG1655, yielding values in agreement with the literature.¹⁷

Theory

 ζ measurements rely on particle velocity estimation. Under an electric field *E* in a microchannel, the electrokinetic velocity v_{EK} of particles in a fluid of viscosity η and permittivity ϵ_{m} is linked to two phenomena: electrophoresis



Fig. 1 Schematic of a microchannel for particle tracking velocimetry (PTV) where charged particles are affected by two forces: electroosmosis (EO) and electrophoresis (EP) when exposed to an electric field. Counter ion charges are represented in blue and surface charges in red.

(EP) due to the zeta potential of the particle ζ_p and electroosmosis (EO) due to the zeta potential of the channel wall ζ_w (Fig. 1).

The electrophoretic component of the velocity has a linear component (proportional to E) and non-linear component (proportional to E^3 or $E^{3/2}$).^{25–27} The nonlinear component can be ignored if the Peclet number is smaller or equal to 1 and the Dukhin number is much smaller than 0.1.^{28,29} The Peclet number corresponds to the ratio of the convective to the diffusive movement of the ions located close to the surface of the particle, while the Dukhin number refers to the ratio of the surface conductivity to the bulk conductivity of the medium. Additionally, the Helmholtz–Smoluchowski model can be applied for particles that are large compared to their EDL (more than a factor 10), which is valid for moderate- to high-ionic strength solutions.¹⁶ For low electric fields, particles are in the linear regime and the total $\nu_{\rm EK}$ can therefore be expressed as eqn (1):

$$\boldsymbol{v}_{\rm EK} = \boldsymbol{\mu}_{\rm EK} \boldsymbol{E} = \left(\boldsymbol{\mu}_{\rm EP} + \boldsymbol{\mu}_{\rm EO}\right) \boldsymbol{E} = \frac{\boldsymbol{\epsilon}_{\rm m}}{\eta} \left(\boldsymbol{\zeta}_{\rm p} - \boldsymbol{\zeta}_{\rm w}\right) \boldsymbol{E}$$
(1)

where μ_{EK} , μ_{EP} and μ_{EO} are the electrokinetic, electrophoretic and electroosmotic mobilities respectively.

The first step in characterization is typically to evaluate ζ_w , generally through various techniques: through the difference of time scale between EO flow and EP,^{30,31} the use of openend and closed-end microchannels³² or current monitoring and/or particle image velocimetry (PIV) or PTV.^{33,34} In classical electrokinetic PTV experiments, v_{EK} is measured at different electric fields *E*. Such PTV measurements typically correspond to several experiments performed consecutively for each value *E*. v_{EK} is plotted as a function of *E* and the associated slope corresponds to μ_{EK} . In the linear regime, μ_{EK} can be linearly correlated to $\zeta_p - \zeta_w$ as expressed in eqn (1).

However, most of these techniques rely on customized equipment, high speed imaging or precise current quantification, making ζ_w measurement challenging.

Materials and methods

Chips

PMMA microchannels with a Luer interface from Microfluidic ChipShop (Jena, Germany) were used in this study. The microchannels have a consistent size: length of 18 mm, height of 100 μ m and width of 100 μ m (Fluidic 157, PMMA, Microfluidic ChipShop, Jena, Germany). 200 μ l polypropylene (PP) reservoirs with Mini Luer interface (Fluidic 934, Microfluidic ChipShop, Jena, Germany) were added on each Luer interface (Fig. 2).

Suspending solution

10 mM *N*-(2-hydroxyethyl)piperazine-*N*'-(2-ethanesulfonic acid) (HEPES) was prepared with HEPES powder Millipore-Sigma (CAS 7365-45-9) in Milli-Q® water. The pH was then adjusted to 7.2 by adding NaOH. The final suspending



Fig. 2 a) Experimental setup with the microfluidic chip and electrodes mounted on an inverted microscope. Reservoirs are pressurized through the modified caps by a pressure controller, and a custom voltage profile is applied by the high voltage sequencer through high voltage cables connected to the platinum electrodes. b) The voltage profile applied to the platinum electrodes with the time-lapse recording window in red.

medium had a conductivity of 172.3 μ S cm⁻¹ and a corresponding Debye length of 7 nm ± 2 nm.³⁵

Particles

1 μm and 2 μm yellow-green fluorescent polystyrene beads with different surface functionalizations (nonfunctionalized polystyrene (PS), sulfate-modified (SU-modified), carboxylatemodified (CO-modified) and amine-modified (AM-modified)) from Invitrogen (Waltham, MA, USA) and Magsphere (Pasadena, CA, USA) were used in this study (Tables S1 and S2†). Stock solutions were diluted in the 10 mM HEPES solution to final concentrations of 10⁸ particles per ml (except the 1 μm AM-modified particles from Magsphere, which were suspended to a concentration of 3 × 10⁹ particles per ml due to their low ζ). All suspensions were prepared 48 h prior to experiments to allow ζ to stabilize. Solutions were vortexed just prior to their addition to the microfluidic chip.

Bacteria samples

E. coli MG1655 (ATCC700926, Manassas, VA, USA) were cultured overnight from individual colonies in Luria–Bertani (LB) broth to stationary phase. Cells were centrifuged at 5000 r.p.m. for 4 min and the supernatant removed. Fresh LB was added, and cells were again centrifuged, constituting a "wash". A total of three LB washes were performed, followed by DAPI staining through the addition of a stock solution of DAPI (4',6-diamidino-2-phenylindole) (CAS 28718-90-3) to a final concentration of 1 μ g ml⁻¹. Samples were covered in foil and allowed to incubate for 10 min. The stained bacteria were then "washed" three times in the 10 mM HEPES suspending solution and resuspended at an optical density at 600 nm (OD₆₀₀) of 0.2 prior to experiments.

Equipment and software

Conductivity and pH were measured respectively using the InLab 741-ISM and InLab Expert Pro ISM with the SevenCompact[™] Duo S213 Benchtop (Mettler Toledo, OH, USA). Time-lapse fluorescent image Columbus, sequences were recorded using a Ti-Eclipse inverted fluorescent microscope (Nikon, Minato City, Tokyo, Japan) with the Zyla 4.2 sCMOS camera (Andor - Oxford Instruments, Abingdon, United Kingdom). The Sequencer software was used to calibrate the high voltage sequencer (Model HVS3000D, LabSmith, Livermore, CA, USA) and a custom LabVIEW[™] program (National Instruments, Austin, TX, USA) was used to apply voltage sequences to the microchannels via platinum electrodes (diameter 584 µm, Pure Platinum Wire, Surepure Chemetals Inc, Florham Park, NJ, USA). Two 25 mbar Flow EZ pressure controllers (Fluigent, Le Kremlin-Bicêtre, France) were used to eliminate flow in the channel by pressurizing the inlet and outlet reservoirs. Control ζ measurements were performed with the Zetasizer Ultra (Malvern Panalytical, Malvern, United Kingdom) (Fig. 3).

Reservoir cap modification

To enable reproducible electrode placement in the reservoirs, the caps of the 200 µl reservoirs with Mini Luer interface were modified to accommodate a pipette tip to pressurize both the inlet and outlet reservoirs (see ESI† for more details). The caps were connected to the pressure controllers through the pressurized 2 ml reservoirs and connection kit (PCAP, Fluigent, Le Kremlin-Bicêtre, France). Tubing was inserted in the modified caps' pipette tips with pressure. Electrodes were inserted on the Mini Luer interface via a Male Mini Luer fluid connector single (Fluidic 331, PP, Microfluidic ChipShop). Electrodes were bent 90° in an L shape of 18 mm \times 10 mm where the tip of the longer side would be in contact with the liquid and the shorter side connected directly to the high voltage sequencer. Precaution in the placement of the electrodes (top of the reservoirs and relatively low electric conductivity suspending medium) were taken to avoid changes (pH and conductivity) in the channel associated with Joule heating and electrochemistry. The full experimental setup is presented in Fig. 2.

Fluid insertion in PMMA chip

The reservoir caps are not air or liquid tight, therefore, a 1 cm \times 1 cm parafilm square (composed of 2 layers of parafilm) with a hole in the center obtained using a 3.5 mm diameter sampling tool (Electron Microscopy Sciences, Hatfield, PA, USA) was used to seal the reservoir when pumping liquid. In total, 400 µl of solution was added to the channel and reservoirs. The channel was viewed under the microscope, and any bubbles in the inlet and outlet reservoirs were removed with a 200 µl pipette tip.

Chip conditioning and applied potentials

A potential difference of 600 V was applied between the inlet and outlet electrodes for 10 min to electrically condition the microchannel containing the 10 mM HEPES, as proposed by Shao and Devoe.³⁶ The voltage difference was applied between 500 V and 1100 V to avoid inaccuracy of the high voltage sequencer at voltages below 100 V (LabSmith). The solution was subsequently removed and replaced with fresh 10 mM HEPES. The voltage sequence employed during the experiment consisted of a voltage ramp between a low hold and a high hold. The voltage sequence applied involved a low voltage hold (25 V) for 25 s followed by a 40 s voltage ramp with a 1 V s⁻¹ increase and a high voltage hold (65 V) for 25 s (Fig. 2b).

Sample insertion in the chip

After conditioning, the fresh 10 mM HEPES was replaced by 400 μ l of the sample suspension with approximately the same volume in both the inlet and outlet reservoirs. The channel was viewed under the microscope, and bubbles in the inlet and outlet reservoirs were removed with a 200 μ l pipette. Both reservoirs were closed with the modified caps, electrodes were placed, and both the inlet and outlet reservoirs were connected to the 25 mbar pressure controllers. The pressure on each reservoir was set to 1 mbar and then adjusted until the beads were no longer moving (zero flow condition). The focusing plane of interest was selected at the channel midplane where beads are moving

the fastest. The 90 s voltage sequence employed during the experiment consisted in a voltage ramp between a low hold and a high hold and is listed above. After 5 s, time-lapse fluorescent images were recorded every 100 ms for 80 s with a 10 ms exposure time. Each channel was used for a single type of particle, and the experiment was repeated eight times. Flow was brought to zero between each experiment.

Data analysis workflow

Recorded time-lapse fluorescent image sequences were automatically analyzed using Matlab, Fiji and the TrackMate plugin.37,38 The contrast of each video was adjusted to facilitate particle discrimination. All parameters for tracking individual particles using PTV were determined by examining the first repeat of each sample type with Fiji and TrackMate. Video analysis was performed using Matlab and ImageJ (ImageJ-MATLAB) to extract the velocity of each particle between each frame. In order to mitigate the effects of incorrectly labelled velocities identified in the PTV data, velocity outliers observed between sequential frames were systematically excluded from the analysis, as detailed in the ESI.† The remaining individual particle velocities were then plotted against time (light blue dots), as well as the median velocity per frame (dark blue line) (Fig. 4). A linear regression was performed during the ramp (between 25 s and 55 s) as well as during the low voltage hold (0 s to 15 s) and the high voltage hold (65 s to 80 s). x_{low} , the abscissa of the intersection between the regressions of the low voltage hold



Fig. 3 Zeta potentials for beads suspended in 10 mM HEPES determined with the Zetasizer Ultra. The mean zeta potential, standard deviation (black error bars) and the zeta potential deviation (red boxes) are shown for each sample (n = 5). The red boxes correspond to the zeta potential deviation (*: all particle suspension concentrations are at 10⁸ particles per ml except the 1 μ m AM-modified particles from Magsphere which is at 3 \times 10⁹ particles per ml).

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Fig. 4 (a) to (i) Representative particle tracking velocimetry (PTV) measurements in the 100 μ m × 100 μ m × 18 mm PMMA microchannels for each type of polystyrene bead suspended in 10 mM HEPES (pH 7.2). (a) 1 μ m SU-modified from Invitrogen, (b) 1 μ m CO-modified from Magsphere, (c) 1 μ m PS from Invitrogen, (d) 1 μ m AM-modified from Invitrogen, (e) 1 μ m CO-modified from Invitrogen, (f) 2 μ m SU-modified from Invitrogen, (g) 1 μ m PS from Magsphere, (h) 2 μ m CO-modified from Invitrogen, (i) 1 μ m AM-modified from Invitrogen, (i) 1 μ m AM-modified from Magsphere. Light blue square: individual velocity; dark blue line: median velocity per frame. PS: polystyrene, SU: sulfate, CO: carboxylate, AM: amine (*: particle suspension concentrations are 10⁸ particles per ml except the 1 μ m Magsphere AM-modified particles from Magsphere which is 3 × 10⁹ particles per ml).

 (y_{low}) and the voltage ramp (y_{ramp}) as well as x_{high} , the abscissa of the intersection between the regressions of the high voltage hold (y_{high}) and the voltage ramp (x_{high}) were calculated along with the difference between both (Δx) . They were compared to the theoretical 40 s duration of the ramp. Additionally, the coefficient of determination (R^2) of the voltage ramp fit y_{ramp} is displayed. Both the R^2 of the voltage ramp fit and the Δx were used to select five repeats among the eight performed, excluding the first repeat performed. The average electrokinetic ramp slope was then calculated as well as the standard deviation and plotted against the ζ obtained with Zetasizer Ultra for a sample of the same batch

(Fig. 5). The full experimental flow chart is available in Fig. S3.†

Results and discussion

Control measurements with the Zetasizer

To obtain ζ_p from an electrokinetic measurement, ζ_w is needed as well as the value of the electric field *E*, which depends on the electrode positioning, as expressed in eqn (1). Since both values are unknown, this requires a characterization step to be able to correlate ζ_p and ν_{EK} . Such reference was obtained measuring ζ of each type of particle

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Fig. 5 Particle electrokinetic velocity slopes of 1 μ m and 2 μ m polystyrene beads with different surface functionalizations, measured by microfluidic electrokinetic characterization, as a function of ζ (Zetasizer Ultra). PS: polystyrene, SU: sulfate, CO: carboxylate, AM: amine. Red line: data fitting.

with the Zetasizer Ultra first (Fig. 3, Tables S1 and S2†). Both the surface chemistry and the manufacturing process impact ζ and all measured values fall within two regimes: between -96 mV and -75 mV and \approx 13 mV. These results were acquired through five measurements of each sample. For each measurement, a ζ distribution is given.

The zeta potential mean (Fig. 3) corresponds to the mean of the mean of each measurement. The standard deviation of the distribution (zeta deviation) shows how broad this deviation is around the mean and corresponds to the halfwidth at half the maximum amplitude of the distribution (ESI†). The zeta deviation was greater than 10 mV for the 2 μ m particles from Invitrogen (SU-modified and CO-modified) as well as the 1 μ m Magsphere AM-modified particles which is more than the double than for the other samples tested. For the 2 μ m particles, the distribution is not Gaussian (ESI†), which is likely a result of the manufacturing process. The 1 μ m Magsphere AM-modified particles have low absolute ζ , indicating that the suspension is less stable.

Determination of individual velocities

All particle velocities were determined through PTV measurement in the microfluidic electrokinetic experimental setup. Fig. 4 presents a representative PTV measurement for each of the different particles, and the mean electrokinetic velocity slopes and corresponding standard deviation of five measurements are presented in Table S1.† All particles except the 1 μ m Magsphere AM-

modified particles show a strong correlation coefficient (above 0.99) between the median electrokinetic velocity during the ramp (between 25 s and 55 s) and the fitted results. At high velocities (high voltage hold), the number of particles per frame increases, decreasing robustness for particle tracking. Assessing the particle velocity at high voltage hold is therefore more subject to errors, impacting the assessment of y_{high} and x_{high} (and therefore Δx). The electrokinetic velocity slope for the 1 µm Magsphere AM-modified particles has a lower coefficient of determination than for other particles which is explained by the intrinsic ζ variability of this sample (ESI†).

Correlation between ζ and electrokinetic velocity slope

As the electrokinetic velocity is proportional to ζ (eqn (1)), we sought to determine the proportionality coefficient between the electrokinetic velocity slope during the ramp, acquired with our method, and the ζ , obtained with the Zetasizer Ultra. Given that we linearly modulate *E* during the ramp by adjusting the voltage within the linear regime, the resultant slope of electrokinetic velocity provides a direct representation of the electrokinetic mobility μ_{EK} and $\zeta_{\text{p}} - \zeta_{\text{w}}$, as formulated in eqn (1). Fig. 5 presents the particle electrokinetic characterization method, as a function of ζ , measured with the Zetasizer. The two measurements are highly correlated ($R^2 = 0.940$). The resultant equation for the fitting is $\gamma = -0.0237x + 0.0547$, with γ being the EK velocity

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slope and *x* the ζ . This equation could also be used to assess ζ_w , which would be 2.3 mV at a zero electrokinetic velocity (*y* = 0). With such a low value, ζ_w can therefore be considered small and the influence of electroosmosis negligible. This method therefore allows us to estimate the wall zeta potential without using current monitoring, which is not feasible here due to the high solution conductivity.²²

As can be seen in Fig. 5, the majority of particles examined cluster is in the ζ region below -75 mV. Yet, studies have shown that bacteria have a ζ between -75 mV and 0 mV around pH 7.39,40 Unfortunately, none of the surfacefunctionalized particles exhibited a ζ in this range. This emphasizes the importance of having samples outside of the lower end of ζ measured (-75 mV) such as the Magsphere 1 μ m AM-modified particles. These exhibit a slightly positive ζ (12.89 mV), which is typically characteristic of an incipient solution instability.⁴¹ Furthermore, these samples are critical to obtain the correlation between the particle electrokinetic velocity slopes, measured by microfluidic electrokinetic characterization, and ζ , obtained with the Zetasizer Ultra. This fitting curve in Fig. 5 can also serve as a calibration curve to extrapolate ζ of samples, such as bacteria, which can be measured with the microfluidic electrokinetic characterization presented but not with the Zetasizer, due to their non-spherical shape.

Assessing the zeta potential of E. coli

The overall goal of this work is to develop an easy-to-use platform to broadly enable ζ measurements. Thus, to expand applications beyond abiotic particles, we applied the workflow to determine the ζ of bacteria. We applied our



Fig. 6 Representative PTV measurements in the 100 μ m × 100 μ m × 18 mm PMMA microchannels for *E. coli* MG1655 suspended in 10 mM HEPES (pH 7.2) at OD = 0.2. Light blue square: individual velocity, dark blue line: median velocity per frame.

microfluidic electrokinetic characterization to *E. coli* MG1655 suspended in 10 mM HEPES. Fig. 6 presents a representative PTV measurement for *E. coli* MG1655. The mean and standard deviation of the electrokinetic velocity slopes obtained from five measurements are 1.097 μ m s⁻² and 0.062 μ m s⁻², respectively. Using the obtained fitting curve, these slopes correspond to ζ of -44 ± 3 mV. This value is similar to what was previously reported for a similar *E. coli* strain (FDA strain Seattle 1946, ATCC 25922) by Antunez-Vela *et al.*¹⁷ They determined ζ as -49 ± 4 mV with a microfluidic electrokinetic characterization performed in a PDMS chip, and 0.2 mM K₂HPO₄ media (41 μ S cm⁻¹) with a pH of 7.3. The similar ζ values across methods validate our workflow and provide further confidence in the platform.

Discussion

The method developed in this study leverages a combination of electrokinetic measurements and correlation with ζ , obtained with a Zetasizer, for different spherical particles to evaluate the zeta potential of E. coli that couldn't be assessed previously due to their non-spherical shape. Most of the deviation from the trend observed in the fitting curve in Fig. 5 is caused by the 1 µm Magsphere CO-modified particles. Those CO-modified particles have been characterized by the manufacturer Magsphere to have a charge density of 0.017 meq g⁻¹ while the charge density isn't provided for PS and AM-modified particles. Such particles appear as an outlier and the discrepancy likely comes from the surface functionalization or Zetasizer measurements, but the explanation is beyond the scope of this study. Excluding that particle type results in an $R^2 = 0.989$ with a linear equation of y = -0.0248x + 0.0325, making ζ_w an estimated 1.3 mV. With such calibration curve the slopes obtained for the *E. coli* samples would correspond to ζ of -43 ± 2 mV which, despite the significant improvement in R^2 , would minimally change the previously estimated ζ of -44 ± 3 mV. Low values of ζ_w for PMMA have been reported for high conductivity solutions.42 In any case, the low value estimated for ζ_w may also indicate that the channel dimensions used in this study hinder electroosmosis.43

This work still relies on a prior zeta potential measurement with a Zetasizer for calibration, measurement that is dependent upon the suspension media used. In the future, reproducible electrode positioning could be corelated to electric field values *E* in the channel, enabling a direct assessment of the electrokinetic mobility $\mu_{\rm EK}$ from the measurement of the electrokinetic velocity $v_{\rm EK}$. Translation into a value of $\zeta_{\rm p}$ would still require a separate assessment of $\zeta_{\rm w}$. An alternative could be to completely suppress electroosmosis using an EOF suppressor.⁴⁴

All the data analysis presented is adjusted for the analysis of monodispersed zeta potential distributions. Future improvement of the algorithm could provide the ability to automatically analyze samples containing multiple distributions. The microchannels used in this study are relatively wide (100 μm \times 100 μm) which could be a limitation to analyze particles smaller than 1 μm . In that case smaller microchannels could be used to perform such characterization at a higher magnification (×40 $\nu s.$ ×20 in this study).

Conclusions

We have developed and validated an experimental setup and data analysis workflow for electrokinetic characterization of particles and cells using commercial chips and open-source software. This commercial platform removes the need for complicated and expensive microfabrication, which involves costly tools that are most often found in cleanrooms. The ability to use off-the-shelf chips while obtaining reproducible results will allow broader access to ζ analysis for the scientific community that may not otherwise have access to necessary resources.

This work is further enabled by particle tracking velocimetry (PTV) using open-source software (Fiji and the TrackMate plugin), which enables the user to tune parameters depending on the sample. Such flexibility also allows characterization of non-spherical particles (such as most cells), which are not compatible with the classical dynamic light scattering (DLS) method used by commercial systems.

Taken together, the novel experimental setup and analysis workflow represent a unique enabling technology for the scientific community. The ability to measure the ζ of a sample of non-spherical particles will have applications well beyond those described here. Nanoparticle research, which currently relies on inaccurate, bulk ζ measurements, will benefit from this workflow, as will the microbiological community, which does not employ ζ as a standard measurement despite its potential utility. When combined with innovations in microscopy, we anticipate this technology being transformative for researchers in reduced resource settings.

Author contributions

Conceptualization J. C., A. L. F. and C. R. B. – data curation J. C. – formal analysis J. C., J. O. O. and A. F. L. – funding acquisition A. L. F. and C. R. B. – investigation J. C., J. O. O. and J. Y. – methodology J. C., A. L. F. and C. R. B. – project administration J. C., A. L. F. and C. R. B. – resources A. L. F. and C. R. B. – software J. C., J. O. O. and A. L. – supervision J. C., A. L. F. and C. R. B. – resources A. L. F. and C. R. B. – software J. C., J. O. O. and A. L. – supervision J. C., A. L. F. and C. R. B. – wisualization J. C., J. O. O. – writing – original draft J. C. – writing – review & editing J. C., A. L. F. and C. R. B.

Conflicts of interest

There are no conflicts to declare.

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