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Graphene foam membranes with tunable pore size for next-generation reverse osmosis water desalination†

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The development of carbon-based reverse osmosis membranes for water desalination is hindered by challenges in achieving a high pore density and controlling the pore size. We use molecular dynamics simulations to demonstrate that graphene foam membranes with a high pore density provide the possibility to tune the pore size by applying mechanical strain. As the pore size is found to be effectively reduced by a structural transformation under strain, graphene foam membranes are able to combine perfect salt rejection with unprecedented water permeability.

Water scarcity is one of the largest global risks¹ with 4.0 billion people living under conditions of severe water stress at least one month of the year during 1996–2006² and the number being predicted to increase to 5.6 billion people in 2050.³ Water desalination by reverse osmosis is a possible solution thanks to the availability of seawater. The method is currently used to produce 65.5 million m³ of desalinated water per day (69% of the total production).⁴ However, the employed polyamide membrane technology suffers from low fouling resistance, low mechanical, chemical, and thermal stabilities, and high energy consumption of 3–4 kW h m^{−3.5} due to the selectivity–permeability trade-off.⁶

Carbon-based nanostructures, including porous graphene, carbon nanotubes, and graphene oxide, provide high chemical and thermal stabilities as well as potential to achieve high salt rejection and water permeability, which is essential for reverse osmosis membranes.⁷ The high water permeability is due to the atomic thickness of porous graphene (mass transport inversely proportional to the membrane thickness according to the Hagen–Poiseuille law)⁸ and the atomically smooth pores (low

New concepts

Reverse osmosis is currently the leading technology for water desalination. However, conventional polyamide membranes suffer from the permeability-selectivity trade-off, *i.e.*, high water permeability comes along with low salt rejection and *vice versa*, causing high energy costs. Alternative techniques based on carbon nanostructures cannot compete with the polyamide membranes due to challenges in controlling the pore density and size. In this study, we discover by molecular dynamics simulations that honeycomb and triangular graphene foam membranes can overcome these challenges by combining a high pore density (two orders larger than in the case of other carbon-based membranes) with the possibility to tune the pore size by applying strain. In particular, we find that strain triggers structural transformations that result in a significant reduction of the pore size. Consequently, honeycomb and triangular graphene foams reject salt perfectly with an unprecedented water permeability. Our work therefore solves the main bottle-neck of the next generation of reverse osmosis membranes. Furthermore, we broaden the fundamental understanding of nanoscale mechanical metamaterials, which will be of great interest to readers from many disciplines.

friction) of carbon nanotubes⁹ and graphene oxide.¹⁰ While both experiments¹¹ and molecular dynamics simulations⁸ show that the single pore water permeabilities are orders of magnitude higher, the effective water permeabilities of porous graphene and carbon nanotube membranes are comparable to those of polyamide membranes because of low pore densities.⁷ The pore size has to exceed a critical value for the water molecules to cross and has to stay below a critical value for the salt ions to be rejected. Unfortunately, control of the pore size is challenging, causing poor salt rejection as compared to polyamide membranes. Defects in porous graphene lead to large pore sizes of 10–150 Å,¹² exceeding the sizes of hydrated Na⁺ (6.6 Å) and Cl[−] (7.2 Å),¹³ and carbon nanotube diameters below 8.1 Å for perfect salt rejection are difficult to achieve.^{14,15} While graphene oxide can be readily fabricated, it swells when subjected to moisture, losing the ability to reject salt ions.¹⁶

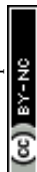
In this study, we use molecular dynamics simulations to investigate the water desalination performance of graphene foam

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membranes, which are stable according to solid state self consistent field¹⁷ and density functional theory^{18,19} predictions. Synthesis of graphene foam has been reported in ref. 20. We demonstrate for graphene foam excellent potential in water desalination due to high pore densities and the possibility to tune the pore size by applying strain. Pore areas from 66 to 396 Å² are found to provide perfect salt rejection with water permeabilities from 14 to 122 l cm⁻² day⁻¹ MPa⁻¹. Importantly, the proposed membranes can be cleaned from fouling by enlarging the pore size through the release of strain.

Results and discussions

The simulation model (Fig. 1a) consists of the graphene foam membrane (Fig. 1b and 1c), the feed zone with 7921 water molecules, 117 Na⁺ ions, and 117 Cl⁻ ions (corresponding to a salt concentration of 1.2 M, *i.e.*, double that of seawater to reduce statistical effects by enhancing the interaction between the ions and membrane), the permeate zone with 2640 water molecules, and two graphene sheets acting as rigid pistons. The size of the simulation box is 50.3 Å in the *x*-direction and 87.1 Å in the *y*-direction. Periodic boundary conditions are applied in all directions, with a 110 Å vacuum layer added in the *z*-direction to avoid spurious interaction.

We consider a graphene foam membrane with an initial pore area (colored blue in Fig. 1b) of 66 Å² and a thickness of 12 Å.

A molecular statics simulation is carried out initially using the conjugate gradient method with a total energy tolerance of 10⁻⁶ between successive iterations, followed by a molecular dynamics simulation at 300 K (canonical ensemble) with an upward/downward pressure of 100.0 MPa applied to the bottom/top piston for 200 ps. Then, the downward pressure is set to 0.1 MPa and the water molecules, Na⁺ ions, and Cl⁻ ions in the permeate zone are counted as a function of the time (Fig. 1e). The water permeability is calculated as $P = v/(A\Delta p)$, where v is the flow rate of water obtained as the slope of a linear fitting curve from time 0 to the moment τ when half of the water molecules have reached the permeate zone, A is the area of the membrane, and Δp is the pressure difference between the feed and permeate zones. The salt rejection is defined as $R = (1 - C_p/C_f) \times 100\%$, where C_p and C_f are the concentrations of salt ions in the permeate and feed zones at time τ , respectively. Further details can be found in the Simulation Methods and a video of the reverse osmosis process is provided as Supporting Information.

We obtain for the graphene foam membrane with an initial pore area of 66 Å² and a thickness of 12 Å a water permeability of 90 l cm⁻² day⁻¹ MPa⁻¹ with perfect salt rejection. In addition,

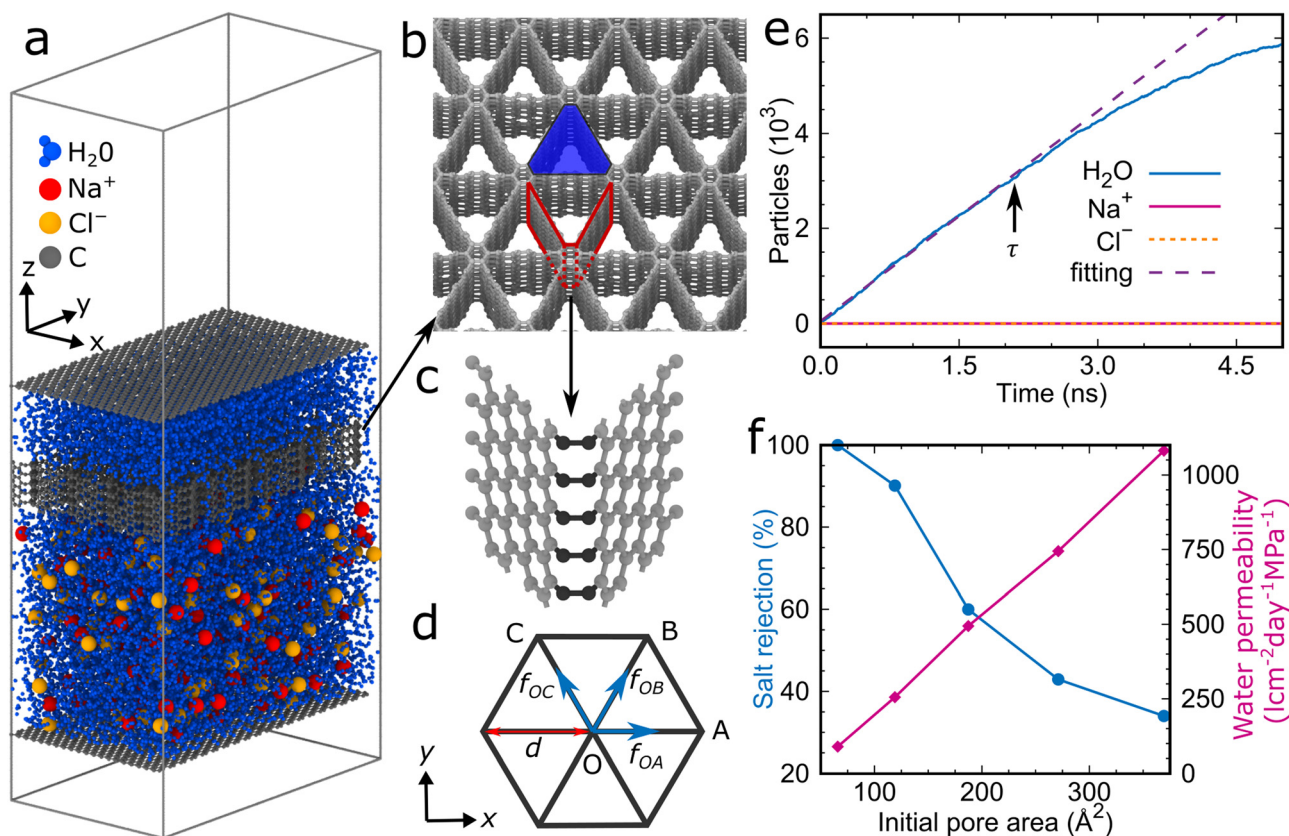


Fig. 1 (a) Simulation model. (b) Perspective view of a portion of the graphene foam membrane. (c) Structure near a junction. (d) Definitions for the continuum model. (e) Number of water molecules, Na⁺ ions, and Cl⁻ ions passing through the unstrained graphene foam membrane with an initial pore area of 66 Å² and a thickness of 12 Å as a function of the time. τ is the time when half of the water molecules have reached the permeate zone. (f) Salt rejection and water permeability of the unstrained graphene foam membrane with a thickness of 12 Å as a function of the initial pore area.

similar to carbon nanotube membranes (where the atomic smoothness of the carbon nanotubes gives rise to a nearly frictionless transport),²¹ it turns out that the water permeability does not depend on the thickness of the graphene foam membrane, as, for example, we obtain the same numerical value when the thickness is multiplied by 10 (Fig. S3 in the ESI†).

To study the effect of the initial pore area on the water desalination performance, we stepwise enlarge it to 369 Å². Fig. 1f shows that the water permeability is enhanced to 1,081 l cm⁻² day⁻¹ MPa⁻¹ (resembling the value of $(1.35 \times 10^{-16} \text{ m}^3 \text{ s}^{-1}) / (480 \text{ MPa} \times 246 \text{ Å}^2) = 988 \text{ l cm}^{-2} \text{ day}^{-1} \text{ MPa}^{-1}$ obtained in ref. 22 for a graphene membrane with circular pores of 246 Å² area and a flow rate of $1.35 \times 10^{-16} \text{ m}^3 \text{ s}^{-1}$ at a pressure of 480 MPa using molecular dynamics simulations and an analytical model, the difference in the required pore area being explained by the different pore shapes) but the salt rejection suffers dramatically (34%). We therefore tune the pore area by applying mechanical strain, see the Simulation Methods for details. Fig. 2 presents the response of the graphene foam membrane with an initial pore area of 187 Å² to strain applied in the *x*- and *y*-directions. The stress-strain curves obtained for the two directions are similar with linear elasticity up to an applied strain of about 0.005 followed by a sudden drop of the stress (Fig. 2a).

The drop can be attributed to buckling of the graphene skeleton: We consider a continuum model based on the

characterized length *d* of the pore (Fig. 1d). In the stress state ($\sigma_x, \sigma_y, \sigma_{xy}$) the forces per unit length (unit N m⁻¹) on the elements OA, OB, and OC (Fig. 1d) are given by²³

$$\begin{bmatrix} f_{OA} \\ f_{OB} \\ f_{OC} \end{bmatrix} = \frac{\sqrt{3}d}{6} \begin{bmatrix} 3 & -1 & 0 \\ 0 & 2 & 2\sqrt{3} \\ 0 & 2 & -2\sqrt{3} \end{bmatrix} \begin{bmatrix} \sigma_x \\ \sigma_y \\ \sigma_{xy} \end{bmatrix}. \quad (1)$$

We have

$$f_{OA} = \frac{\sqrt{3}}{2} d \sigma_x, \quad f_{OB} = f_{OC} = 0 \quad (2)$$

for compression in the *x*-direction ($\sigma_x \neq 0, \sigma_y = 0, \sigma_{xy} = 0$) and

$$f_{OA} = -\frac{1}{2\sqrt{3}} d \sigma_y, \quad f_{OB} = f_{OC} = \frac{1}{\sqrt{3}} d \sigma_y. \quad (3)$$

for compression in the *y*-direction ($\sigma_x = 0, \sigma_y \neq 0, \sigma_{xy} = 0$). If the elements buckle before any other failure, the critical force per unit length, according to the Euler buckling theory, is given by

$$f^{\text{cr}} = n^2 \frac{\pi^2 D}{d^2}, \quad (4)$$

where *n* describes the rotation constraint of the ends of the elements (*n* = 0.5: free rotation; *n* = 2.0: fixed rotation) and *D* is the bending stiffness. Eqn (2)–(4) imply that the critical stress for

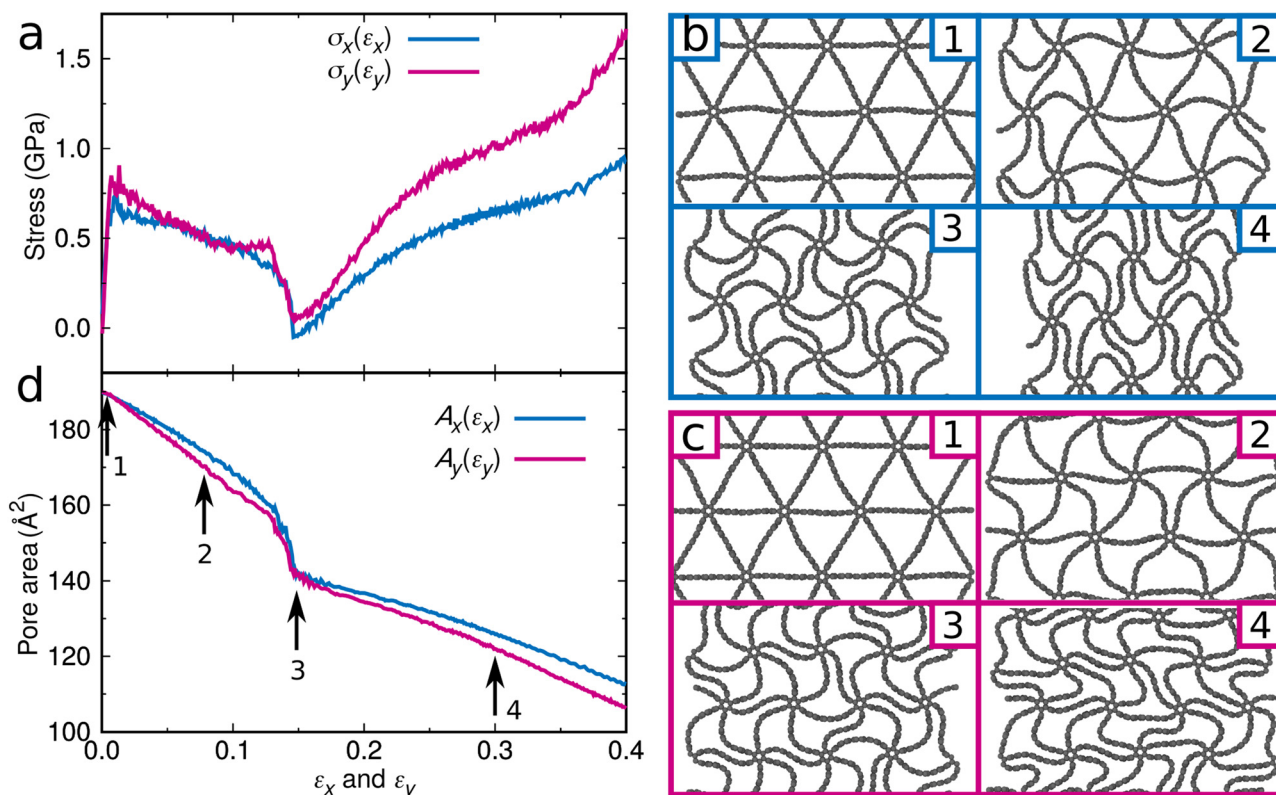


Fig. 2 Graphene foam membrane with an initial pore area of 187 Å²: (a) Stress-strain curves for loading in the *x*- and *y*-directions. Structure under increasing strain (0.005, 0.075, 0.150, and 0.300) applied in the (b) *x*- and (c) *y*-directions. (d) Pore area as a function of the strain applied in the *x*- and *y*-directions.



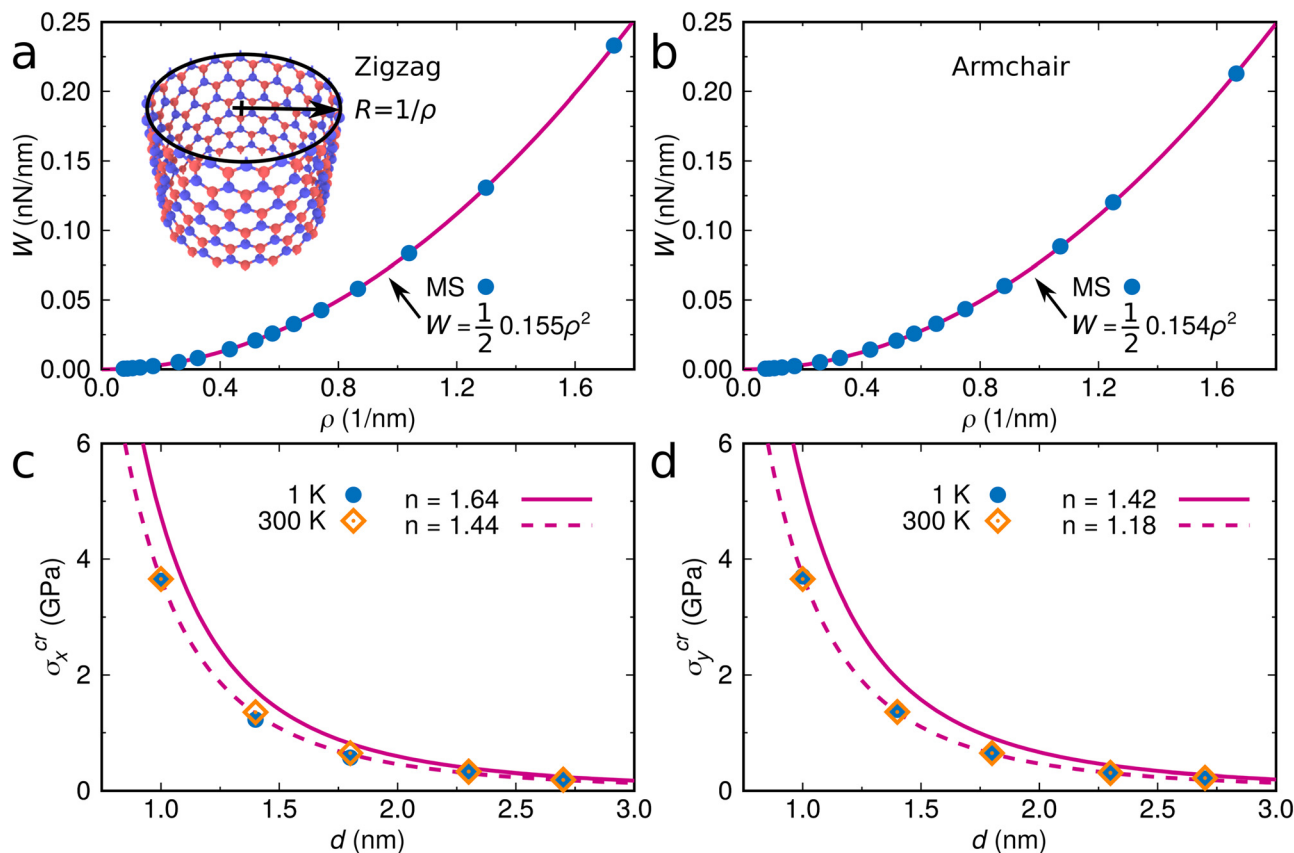


Fig. 3 Bending energy density of a carbon nanotube (inset) as a function of the bending curvature for the (a) zigzag and (b) armchair directions. Critical stress for buckling in a graphene foam membrane as a function of the characteristic length of the pore for loading in the (c) x- and (d) y-directions.

buckling is

$$\sigma_x^{\text{cr}} = \frac{2}{\sqrt{3}} \frac{n^2 \pi^2 D}{d^3} \quad (5)$$

for loading in the x-direction and

$$\sigma_y^{\text{cr}} = \sqrt{3} \frac{n^2 \pi^2 D}{d^3}. \quad (6)$$

for loading in the y-direction.

Classical plate theory cannot be used to calculate the bending stiffness directly from Young's modulus E and Poisson's ratio ν as $D = Et^3/12(1 - \nu^2)$, because the thickness t is not well-defined in the case of bending. Instead, the bending stiffness is obtained from the relation

$$W = \frac{1}{2} D \rho^2, \quad (7)$$

where W is the energy density (unit nN nm^{-1}) associated with the bending of graphene (bending curvature ρ). We follow the established methodology and study graphene rolled into a carbon nanotube with radius $R = 1/\rho$ by molecular statics simulations.²⁴ To eliminate in-plane strain and ensure pure bending, a periodic boundary condition is applied in the axial direction of the carbon nanotube with fixed length and only half of the atoms (the blue atoms in the inset of Fig. 3a) are

allowed to relax in order to maintain the radius. The bending stiffness then is derived by fitting the data to Eqn (7). We obtain values of 0.155 nN nm (Fig. 3a) and 0.154 nN nm (Fig. 3b) for the zigzag and armchair directions, respectively.

It turns out that Eqn (5) and (6) agree well with the trend ($\propto d^{-3}$) obtained by molecular dynamics simulations for the critical stress as a function of the characteristic length of the pore (Fig. 3c and d). Fitting of the data leads to $n = 1.44$ for loading in the x-direction and $n = 1.18$ for loading in the y-direction. These values are smaller than predicted by column-beam theory (1.64 and 1.42, respectively²⁵), because the assumption of linearly connected elements is violated (ring-like connection; Fig. 1d). Note that temperature effects on the critical stresses are small (Fig. 3c and d).

The buckling triggers a structural transformation in the graphene foam membrane when strain is applied (Fig. 2b and c). This localized and fully elastic (*i.e.*, reversible) transformation is complete at an applied strain of about 0.15, while at higher applied strain the new shape is further accentuated. The buckling will affect the water desalination performance, as the pore area decreases (Fig. 2d). For example, strain of 0.015 applied in the x-direction of the graphene foam membrane with an initial pore area of $187 \text{ \AA}^2$ significantly enhances the salt rejection from 60% to 96%. Perfect salt rejection is achieved at $\varepsilon_x^{100} = 0.35$ (Fig. 4a), which corresponds to a pore area of $119 \text{ \AA}^2$ (Fig. 2d). Note that the salt rejection of the



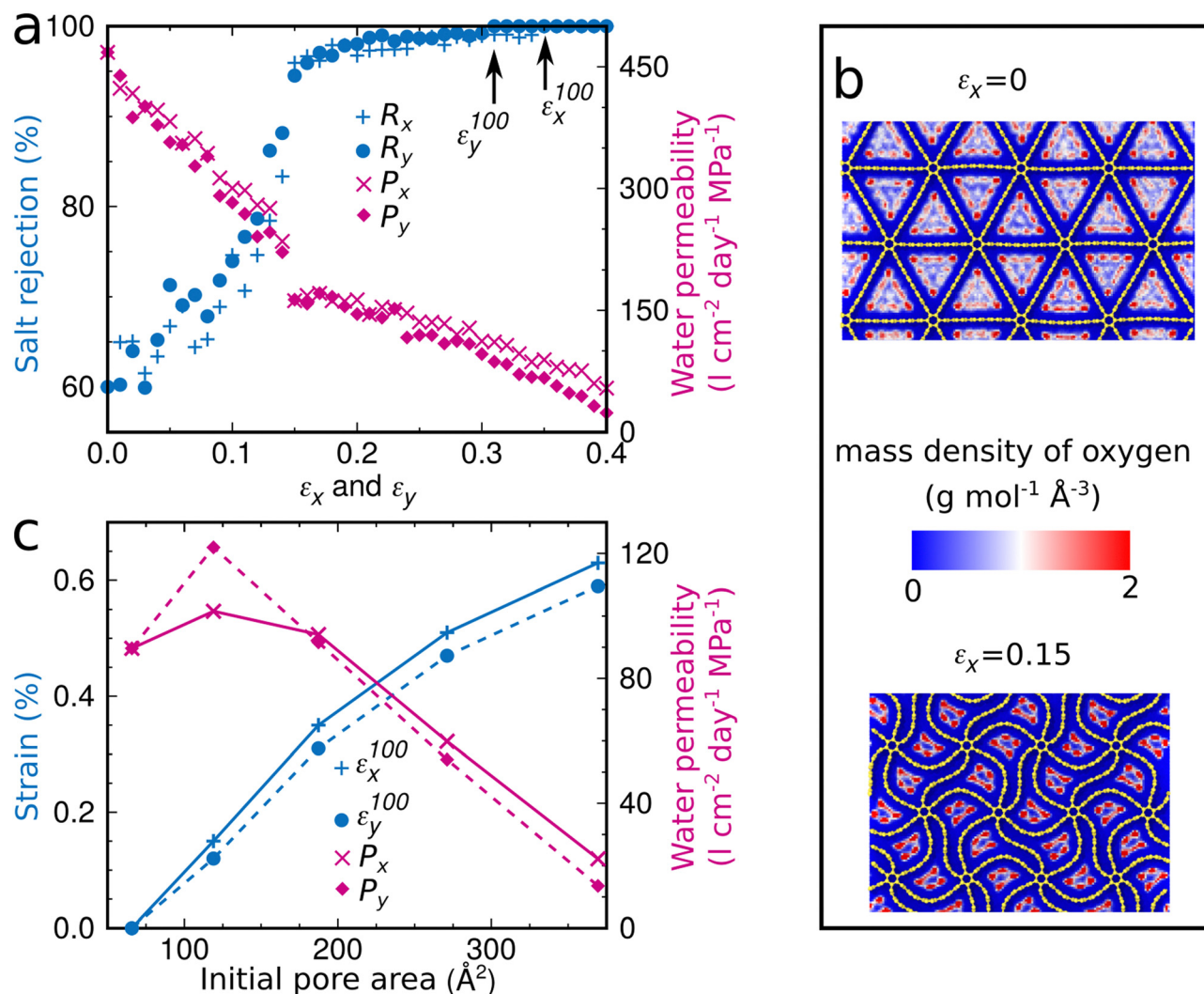


Fig. 4 (a) Salt rejection and water permeability as a function of the strain applied in the x- and y-directions for an initial pore area of 187 Å². (b) Effect of the strain applied in the x-direction on the mass density of oxygen inside the pores for an initial pore area of 187 Å². (c) Applied strain required for perfect salt rejection and corresponding water permeability as a function of the initial pore area.

unstrained graphene foam membrane with an initial pore area of 119 Å² is only 90% (Fig. 1f), indicating that the effective pore area under strain is much smaller. The reason is that the special pore shape (narrow at one end and wider at the other end) induced by the structural transformation allows passage only at the wider end (Fig. 4b). A similar behavior is observed for loading in the y-direction with perfect salt rejection achieved at $\epsilon_y^{100} = 0.31$. The slightly lower water permeability and higher salt rejection as compared to loading in the x-direction are consistent with the slightly smaller pore area (Fig. 2d). While maintaining perfect salt rejection, ultrahigh water permeabilities of $P_x^{100} = 94$ l cm⁻² day⁻¹ MPa⁻¹ and $P_y^{100} = 92$ l cm⁻² day⁻¹ MPa⁻¹ are achieved for loading in the x- and y-directions, respectively. We also find that ϵ_x^{100} and ϵ_y^{100} increase when the initial pore area increases from 66 to 396 Å², whereas P_x^{100} and P_y^{100} decrease (Fig. 4c). For a given initial pore area, the desalination conditions are best at ϵ_x^{100} and ϵ_y^{100} for loading in the x- and y-directions, respectively, because the salt rejection is perfect with the largest water permeability (Fig. 4a). Our simulation

results therefore demonstrate that tuning of the pore area by applying mechanical strain is a highly effective strategy to obtain graphene foam membranes that combine perfect salt rejection with ultrahigh water permeability.

While the water permeability through a single pore is of the same order of magnitude as reported for graphyne,²⁶ porous graphene,⁸ and carbon nanotube¹⁴ membranes, the intrinsic pore densities of graphene foam (from 0.7×10^{14} cm⁻² to 1.5×10^{14} cm⁻²) and graphyne (9.3×10^{14} cm⁻²) membranes are

Table 1 Water permeability of the graphene foam membrane with an initial pore area of 66 Å² compared to other materials with perfect salt rejection

	P (l cm ⁻² day ⁻¹ MPa ⁻¹)
Graphene foam	13–121 (this study)
Graphyne	17 ²⁶
Carbon nanotube	38 ¹⁴ (for the maximal pore density)
Porous graphene	66 ⁸ (for a porosity of 10%)
Polyamide	0.03 ²⁷



Table 2 Potential parameters and charges

	C	H	O	Na ⁺	Cl ⁻
ϵ (kcal mol ⁻¹)	0.134	0	0.1553	0.3526	0.0128
σ (Å)	3.214	0	3.166	2.424	5.422
Charge (electrons)	0	+0.4238	-0.8476	1	-1
Potential	Lennard-Jones	SPC/E	SPC/E	Coulombic + Lennard-Jones	Coulombic + Lennard-Jones
Ref.	30	31	31	32	32

much larger than the extrinsic pore densities of porous graphene ($1.0 \times 10^{12} \text{ cm}^{-2}$) and carbon nanotube ($2.5 \times 10^{11} \text{ cm}^{-2}$) membranes. As a result, the water permeabilities of the graphene foam and graphyne membranes are two orders of magnitude larger, and even three orders of magnitude as compared to conventional polyamide membranes²⁷ (see Table 1 for a comparison). While tension can be used to enlarge the pores of graphene foam membranes and some two-dimensional materials,^{28,29} pore size reduction for perfect salt rejection (the most challenging issue of the next generation of membranes) by compression is only possible in the case of graphene foam membranes. While the pore size of graphene foam membranes can be controlled by compression due to buckling of the graphene skeleton (resulting from the atomic thickness of graphene), it is impossible to control the pore size of graphyne or any other two-dimensional material by compression due to the possibility of out-of-plane buckling. In contrast to the model employed in this study for describing graphene foam membranes, in reality the pores may not be perfectly directional and they may have different sizes and shapes, though highly directional pores were observed in graphene foam by high resolution transition electron microscopy.²⁰ We find that the graphene skeleton buckles irrespective of the pore size (Fig. 4c). It also buckles irrespective of the pore shape and in the case of a non-uniform membrane with pores of different sizes and shapes (Fig. S4 in the ESI†), which implies that the pore size still can be tuned by strain.

In conclusion, graphene foam membranes are found to overcome the limitations of conventional polyamide membranes and existing carbon-based membranes for water desalination. The excellent performance of the graphene foams originates as follows: first, while low friction of water is common to carbon nanotubes and graphene foam, the high pore density of graphene foam results in ultrahigh water permeability. Second, due to the combination of periodic pores with the atomic thickness of graphene in a special three-dimensional geometry, graphene foam membranes undergo under mechanical strain a unique structural transformation based on buckling of the graphene skeleton, which results in tunability of the pore size. Third, while usually a large pore size is detrimental for the salt rejection, this does not apply to graphene foam membranes, because the pore size can be effectively reduced by applying mechanical strain. Importantly, the structural transformation is reversible, *i.e.*, the initial (large) pore size can be restored for cleaning the membrane from fouling. These extraordinary properties let graphene foam membranes emerge as ideal candidates for reverse osmosis water desalination.

Simulation methods

Water is modeled using the SPC/E potential³¹ with the SHAKE algorithm (tolerance of 10^{-5})³³ to keep the O–H distance at 1 Å and the H–O–H angle at 109.47°. The interaction between the C atoms is modelled by the AIREBO potential³⁴ (which reproduces Young's modulus and Poisson's ratio of the graphene foam membrane and the interlayer binding energy of graphite obtained by first-principles calculations and experiment; see the Supporting Information for details). Other interactions are modelled by Lennard-Jones potentials $V(r) = 4\epsilon[(\sigma/r)^{12} - (\sigma/r)^6]$ (where r is the distance, ϵ is the well depth, and $V(\sigma) = 0$) and Coulombic terms,^{30,32} using cutoff radii of 10.2 Å. We employ the parameters given in Table 2 and calculate those between different species by the Lorentz–Berthelot combination rules.^{35,36} The particle–particle particle-mesh method³⁷ is employed to compute the long-range Coulombic interactions of the ions. The water-salt solutions are generated by PACKMOL.³⁸ Two graphene sheets act as rigid pistons by setting the force components of each atom to zero in the x - and y -directions. The graphene foam membrane initially is relaxed at 300 K for 100 ps, using a isothermal-isobaric ensemble. Then compressive strain is applied in the x - or y -direction with a rate of 10^8 s^{-1} (where we assume that the pores are empty), using an isothermal-isobaric ensemble. The resulting stress in the y - or x -direction is controlled to be zero to simulate uniaxial stress. A Nose–Hoover thermostat^{39,40} is used to control the temperature and a Nose–Hoover barostat^{41,42} is used to control the pressure. All molecular dynamics simulations are performed by the LAMMPS code⁴³ with a time step of 1 fs. During the reverse osmosis process, few atoms of the graphene foam membrane are fixed to prevent movement due to the applied pressure and for the others we fix the z -positions to decouple the deflection from the salt and water transport. Note that the deflection is reduced significantly in a thick graphene foam membrane according to plate theory.⁴⁴ Estimation of statistical uncertainties by repetition of the molecular dynamics simulations is inhibited by the high consumption of computational resources.

Data availability

The authors declare that the data supporting the findings of this study are available within the paper.

Author contributions

D. T. H. performed the molecular statics and molecular dynamics simulations. A. J. performed the first-principles calculations.



D. T. H. and T. P. N. N. wrote the initial draft of the manuscript. U.S. contributed to the data analysis and revised the manuscript.

Conflicts of interest

The authors declare no competing interests.

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